

A) 1) x obeys $p_0(x) = \frac{1}{\mu} e^{-x/\mu}$

$$\langle x \rangle = \mu ; \quad \langle x^2 \rangle = 2\mu^2$$

$$V(x) = \langle x^2 \rangle - \langle x \rangle^2 = \mu^2$$

$$\langle S_n \rangle = n\mu$$

$$V(S_n) = n\mu^2$$

2) The CLT applies in a region of extinction $n^{2/3}$ around $S_n = n\mu$ (see below, 5^o)

$$P(S_n) \approx \frac{1}{\sqrt{2\pi n\mu^2}} \exp\left[-\frac{(S_n - n\mu)^2}{2n\mu^2}\right]$$

3) Sanov theorem: $P(S_n) \approx e^{-n\phi(\bar{z})}$; $\bar{z} = \frac{S_n}{n}$. where $\phi(\bar{z}) = D[q^* || p_0]$, Kullback-Leibler and $q^* = \arg\min D[q || p_0]$ s.t. $\int q(x)dx = \bar{z}$

We thus minimize $D[q || p_0]$ with the constraints that $\int q(x)dx = 1$; $\int q(x)x dx = \bar{z}$

$$\sum_{x \in \Omega} q(x) \left[\int dx \left(q(x) \log \frac{q(x)}{p_0(x)} + \lambda x q(x) + \mu q(x) \right) \right] = 0$$

$$\Rightarrow \log \frac{q(x)}{p_0(x)} + \lambda x + \mu = 0$$

$$\Rightarrow q(x) = \frac{1}{\mu} e^{-\frac{\lambda x}{\mu}} e^{-\mu}$$

and since we need $\int q(x)x dx = \bar{z}$, we get the only possibility

$$q(x) = \frac{1}{\bar{z}} e^{-x/\bar{z}}$$

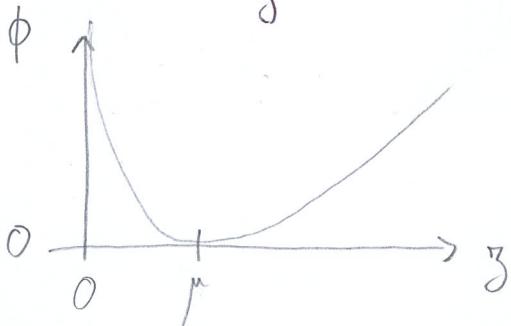
$$\Rightarrow \phi(\bar{z}) = \int dx q(x) \log \left(\frac{q(x)}{p_0(x)} \right)$$

$$= \int dx \frac{1}{\bar{z}} e^{-x/\bar{z}} \left[\log\left(\frac{1}{\bar{z}}\right) + x\left(\frac{1}{\mu} - \frac{1}{\bar{z}}\right) \right]$$

$$\phi(\bar{z}) = -1 + \frac{3}{\mu} - \log \frac{3}{\mu}$$

$$\phi'(\bar{z}) = \frac{1}{\mu} - \frac{1}{\bar{z}} \quad \text{and } \phi(\mu) = \phi'(\mu) = 0$$

$$\phi''(\bar{z}) = \frac{1}{\bar{z}^2}$$



4) The CLT predicts a quadratic $\phi(\bar{z})$:

$$P(S_n) \approx \exp\left[-\frac{n}{2}\left(\frac{\bar{z}-\mu}{\mu}\right)^2\right]$$

hence $\phi(\bar{z}) = \frac{1}{2}\left(\frac{\bar{z}-\mu}{\mu}\right)^2$

We can recover this from a Taylor expansion of Eq(1): for small $\delta\bar{z}$,

$$\phi(\mu + \delta\bar{z}) \approx \frac{1}{2}\frac{1}{\mu^2}(\delta\bar{z})^2$$

5) We have $\phi(\bar{z}) \approx \frac{1}{2}\phi''(\mu)(\bar{z}-\mu)^2 + \frac{1}{6}\phi'''(\mu)(\bar{z}-\mu)^3 + \dots$

and the CLT holds provided

$$\left| n\phi'''(\mu)(\bar{z}-\mu)^3 \right| \ll 1$$

$$\Leftrightarrow n \left| \frac{\bar{z}-\mu}{\mu} \right|^3 \ll 1$$

$$\Leftrightarrow \left| \frac{\bar{z}-\mu}{\mu} \right| \ll n^{2/3}$$

6) $\langle e^{tS_n} \rangle = \int e^{tS_n} P(S_n) dS_n$

$$= \int e^{tS_n} e^{-n\phi(\bar{z})} dS_n$$

$$= e^{n \max_{\bar{z}} [t\bar{z} - \phi(\bar{z})]}$$

$S_n = n\bar{z}$
from saddle argument

$$\text{Besides, } \langle e^{tS_m} \rangle = \langle e^{tx_i} \rangle^n$$

$$\Rightarrow S(t) = \max_{\bar{x}} [\bar{x}t - \phi(\bar{x})]$$

which is inverted in

$$\phi(\bar{x}) = \max_t [\bar{x}t - S(t)]$$

$$K_m(t) = \frac{1}{m} \log \langle e^{tS_m} \rangle = \frac{1}{m} \log \langle e^{tx_i} \rangle^n$$

$$= \log \langle e^{tx_i} \rangle \quad \begin{matrix} \text{does not depend on} \\ m \text{ since } x_i \text{ are} \\ \text{independent} \end{matrix}$$

$$\langle e^{tx_i} \rangle = \frac{1}{\mu} \int_0^\infty e^{tx_i} e^{-x/\mu} dx$$

$$= \mu \left(\frac{1}{\mu} - t \right)^{-1} = \frac{1}{1 - \mu t}$$

$$\frac{1}{\mu} - t > 0 \Leftrightarrow \mu t < 1$$

$$S_m(t) = -\log(1 - \mu t)$$

$$\text{To get } \phi(\bar{x}): \frac{d}{dt} (\bar{x}t - S(t)) = 0 = \bar{x} + \frac{-\mu}{1 - \mu t}$$

$$\Leftrightarrow \mu t^* = 1 - \frac{\mu}{\bar{x}}$$

$$t^* = \frac{\bar{x} - \mu}{\mu \bar{x}}$$

$$\phi(\bar{x}) = \bar{x}t^* - S(t^*)$$

$$= \frac{\bar{x} - \mu}{\mu} + \log(1 - 1 + \frac{\mu}{\bar{x}})$$

$$\phi(\bar{x}) = \frac{\bar{x}}{\mu} - 1 - \log\left(\frac{\bar{x}}{\mu}\right)$$

same result
as with
Savov thm

$$\text{with } \phi(z) = \frac{z}{\mu} - \log\left(\frac{z}{\mu}\right) + \text{const} \quad (2)$$

and we need that $\phi = 0$ at its minimum,
which is for $\bar{x} = \mu \Rightarrow \text{const} = -1$.

f) For large m , the most probable value of S_m is $n\mu$, and around it, the CLT applies:

$$\Pr\left[\left(n - \frac{1}{2}\right)\mu \leq S_m \leq \left(n + \frac{1}{2}\right)\mu\right]$$

$$= \int_{\left(n - \frac{1}{2}\right)\mu}^{\left(n + \frac{1}{2}\right)\mu} \Pr(S_m) dS_m$$

$$= \int_{n-\frac{1}{2}}^{n+\frac{1}{2}} e^{-s} \frac{d}{(n-1)!} s^{n-1} ds$$

$$= \int_{n-\frac{1}{2}}^{n+\frac{1}{2}} \frac{1}{\sqrt{2\pi n}} e^{-\frac{(s-n)^2}{2n}} ds \quad \text{from CLT}$$

$$\sim \frac{1}{\sqrt{2\pi n}} \quad \text{for } n \text{ large}$$

One can show that

$$\int_{n-\frac{1}{2}}^{n+\frac{1}{2}} e^{-s} \frac{d}{(n-1)!} s^{n-1} ds \sim e^{-n} \frac{n^{n-1}}{(n-1)!}$$

$$= e^{-n} \frac{n^n}{n!}$$

$$\Rightarrow e^{-n} \frac{n^n}{n!} \sim \frac{1}{\sqrt{2\pi n}}$$

$$\therefore n! \sim \sqrt{2\pi n} \left(\frac{n}{e}\right)^n \quad \text{Stirling formula}$$

$$\text{Proof that } \Pr(S_m) = \frac{1}{\mu} \frac{1}{(n-1)!} e^{-\frac{S_m}{\mu}} \left(\frac{S_m}{\mu}\right)^{n-1}$$

$$S_m = \sum_{i=1}^n x_i$$

Each x_i is drawn according to an exponential law and thus, the largest n such that $S_m \leq S$ obeys a Poisson distribution

$$\Pr(S_m) \sim \frac{1}{\mu} e^{-\frac{S_m}{\mu}} \left(\frac{S_m}{\mu}\right)^{n-1}$$

From Stirling, but not needed

$$= e^{-n} \phi(\bar{x})$$

$$= e^{-n} \phi(\bar{x})$$

$P(S/\mu)$ - Take N , a random variable following $P(S/\mu)$: $\begin{array}{c} 0 \\ \vdash \\ 1 \\ \times \\ 2 \\ \times \\ 3 \\ \vdash \\ 4 \end{array}$

$$P[N > n_0] = P[S_{n_0} \leq S]$$

$$\Leftrightarrow \sum_{N=n_0}^{\infty} e^{-S/\mu} \frac{(S/\mu)^N}{N!} = \int_0^S P_{n_0}(s) ds$$

Then, take $\partial/\partial S$ on both sides:

$$\begin{aligned} P_{n_0}(S) &= \frac{\partial}{\partial S} \sum_{N=n_0}^{\infty} e^{-S/\mu} \frac{(S/\mu)^N}{N!} \\ &= \frac{1}{\mu} \sum_{N=n_0}^{\infty} \left(\frac{(S/\mu)^{N-1}}{(N-1)!} e^{-S/\mu} - \frac{(S/\mu)^N e^{-S/\mu}}{N!} \right) \\ &= \frac{1}{\mu} \frac{1}{(n_0-1)!} e^{-S/\mu} \left(\frac{S}{\mu} \right)^{n_0-1} \end{aligned}$$

(B) 1) With Itô-Döblin

$$\frac{d}{dt} \langle \varphi(v) \rangle = \langle \varphi'(v) v \rangle + \Gamma \langle \varphi''(v) \rangle$$

since Γ is here the diffusion coefficient

$$\varphi(v) = v^2$$

$$\begin{aligned} \frac{d \langle v^2 \rangle}{dt} &= 2 \langle v v \rangle + 2 \Gamma \\ &= 2 \langle v(-\gamma v + \sqrt{2\Gamma} \xi(t)) \rangle + 2 \Gamma \\ &= -2\gamma \langle v^2 \rangle + 2 \Gamma \end{aligned}$$

Since $\langle v(t) \xi(t) \rangle = 0$ at Itô-Döblin level

$$2) \quad \frac{d}{dt} \left(\langle v^2 \rangle \frac{\Gamma}{8} \right) = -2\gamma \left(\langle v^2 \rangle \frac{\Gamma}{8} \right)$$

$$\Rightarrow \langle v^2 \rangle - \frac{\Gamma}{8} = A e^{-2\gamma t}; \quad \langle v^2 \rangle = v_0^2 \text{ at } t=0$$

$$\Rightarrow A = v_0^2 - \frac{\Gamma}{8}$$

$$\Rightarrow \langle v^2(t) \rangle = \frac{\Gamma}{8} \left(1 - e^{-2\gamma t} \right) + v_0^2 e^{-2\gamma t}$$

$$\langle v^2(t) \rangle = \left(v_0^2 - \frac{\Gamma}{8} \right) e^{-2\gamma t} + \frac{\Gamma}{8} \quad (3)$$

3) Within stationary framework

$$\frac{d \langle v^2 \rangle}{dt} = 2 \langle v v \rangle$$

$$= -2\gamma \langle v^2 \rangle + 2\sqrt{2\Gamma} \underbrace{\langle v(t) \xi(t) \rangle}_{\neq 0}$$

$$\Leftrightarrow \left\langle \frac{v(t) + v(t+\Delta t)}{2\Delta t} \right\rangle \underbrace{\int_t^{t+\Delta t} \xi(t') dt'}_{B_{\Delta t}}$$

$$\langle v(t+\Delta t) \rangle = \langle v(t) \rangle - \gamma \langle v(t) \rangle \Delta t + \sqrt{2\Gamma} B_{\Delta t} + \dots$$

$$\langle B_{\Delta t} \rangle = 0; \quad \langle B_{\Delta t}^2 \rangle = \Delta t$$

$$\Delta \left\langle \frac{1}{2\Delta t} \langle v(t+\Delta t) \rangle B_{\Delta t} \right\rangle$$

$$= \frac{1}{2} \sqrt{2\Gamma} \langle B_{\Delta t}^2 \rangle \frac{1}{\Delta t}$$

$$= \frac{1}{2} \sqrt{2\Gamma}$$

$$\Rightarrow \frac{d \langle v^2 \rangle}{dt} = -2\gamma \langle v^2 \rangle + 2\Gamma$$

as found above

4) We know that the velocity pdf is gaussian at all times; hence the skewness is always 0. This can be recovered by calculation, but we need to adapt slightly Itô-Döblin calculus to a function $\varphi(v, t)$

$$\begin{aligned} \frac{d}{dt} \langle \varphi(v, t) \rangle &= \left\langle \frac{\partial \varphi}{\partial t} \right\rangle + \left\langle \frac{\partial \varphi}{\partial v} v \right\rangle \\ &\quad + \Gamma \left\langle \frac{\partial^2 \varphi}{\partial v^2} \right\rangle \end{aligned}$$

$$\text{Here } \varphi(v, t) = (v - \langle v \rangle)^3 e^{-\gamma t}$$

$$\langle v \rangle = v_0 e^{-\gamma t}$$

$$\frac{\partial \varphi}{\partial t} = +3(v - \langle v \rangle)^2 \gamma \langle v \rangle$$

$$\frac{\partial^2 \varphi}{\partial v^2} = 3(v - \langle v \rangle)^2$$

$$\begin{aligned} \frac{d}{dt} \langle (r - \langle r \rangle)^3 \rangle &= 3\langle r \rangle \langle (r - \langle r \rangle)^2 \rangle \\ &+ \underbrace{\left\langle 3(r - \langle r \rangle)^2 \frac{dr}{dt} \right\rangle}_{-3\langle r(r - \langle r \rangle)^2 \rangle} + \underbrace{16\langle r - \langle r \rangle \rangle}_0 \\ &= -3\langle (r - \langle r \rangle)^3 \rangle \end{aligned}$$

Hence a solution $\langle (r - \langle r \rangle)^3 \rangle = B e^{-3\sigma^2 t}$

and the initial condition is such that $B=0$
 \hookrightarrow vanishing skewness. We would get the same conclusion with the 4th cumulant

C Geometric Brownian motion

1) At stationary level, standard rules of calculus apply : $\frac{1}{S} \frac{dS}{dt} = \mu - \frac{\sigma^2}{2} + \sigma S(t)$

$$\begin{aligned} &= \frac{d}{dt} \ln S \\ \Rightarrow \ln S(t) &= \underbrace{\ln S(0)}_0 + \left(\mu - \frac{\sigma^2}{2} \right) t + \underbrace{\sigma \int_0^t S(t') dt'}_{X(t)} \end{aligned}$$

$X(t)$ is a Wiener process, $\langle X(t) \rangle = 0$
 $\langle X^2(t) \rangle = \sigma^2 t$

(hence a diffusion coefficient $\sigma^2/2$)

$$S(t) = \exp \left[\left(\mu - \frac{\sigma^2}{2} \right) t + X(t) \right]$$

$X(t)$ is a Gaussian process $\stackrel{D}{\sim} \mathcal{N}(0, t)$
 $\langle X(t) \rangle = 0$ and $\langle X(t) X(t') \rangle = \sigma^2 \min(t, t')$

2) For a Gaussian X of mean m and variance σ^2 :

$$\begin{aligned} \langle e^{kX} \rangle &= e^{km} e^{\frac{k^2 \sigma^2}{2}} \\ \Rightarrow \langle S^m(t) \rangle &= e^{m(\mu - \frac{\sigma^2}{2})t} \underbrace{\langle e^{mX} \rangle}_{e^{\frac{m^2 \sigma^2 t}{2}}} \end{aligned}$$

since $m^2 = \sigma^2 t$ here

$$\begin{aligned} \langle S(t) \rangle &= e^{\mu t} = e^{\mu t} \\ \langle S^2(t) \rangle &= e^{2\mu t + \sigma^2 t} \\ \langle S^m(t) \rangle &= e^{m\mu t + \frac{\sigma^2 t}{2} (m^2 - m)} \end{aligned} \quad (4)$$

$(\alpha = 1)$

3) The distribution of $X(t)$ is Gaussian :

$$p_X(x) = \frac{1}{\sqrt{2\pi\sigma^2 t}} \exp \left[-\frac{x^2}{2\sigma^2 t} \right]$$

and $\log S = \left(\mu - \frac{\sigma^2}{2} \right) t + X$

$$\begin{aligned} p(S) dS &= p_X(X) dX \\ \frac{d \log S}{dX} &= 1 \Rightarrow \frac{dS}{dX} = S \\ \Rightarrow p(S,t) &= \frac{1}{S} \frac{1}{\sqrt{2\pi\sigma^2 t}} \exp \left[-\frac{\left[\log S - \left(\mu - \frac{\sigma^2}{2} \right) t \right]^2}{2\sigma^2 t} \right] \end{aligned}$$

\hookrightarrow LOG-NORMAL LAW

When t is large, and for $|\log S| \ll \sigma^2 t$, we have

$$p(S,t) \approx \frac{1}{S} \exp \left[\frac{2(\log S)(\mu - \frac{\sigma^2}{2})}{2\sigma^2} \right]$$

$$\begin{aligned} &\approx \frac{1}{S} S \\ &\approx S^{-\frac{3}{2} + \mu/\sigma^2} \end{aligned}$$

4) Fokker-Planck:

$$\begin{aligned} \partial_t p(S,t) &= -\partial_S \left[\left(\mu - \frac{\sigma^2}{2} \right) S p(S,t) \right] \\ &+ \frac{\sigma^2}{2} \partial_S \left[S \partial_S (Sp) \right] \end{aligned}$$

5) Constraint $S \geq S_{\min}$ added (a "wall")

Steady state for:

$$\partial_S \left[\left(\mu - \frac{\sigma^2}{2} \right) S p(S) \right] = \frac{\sigma^2}{2} \partial_S [S \partial_S (Sp)]$$

and equilibrium corresponds to a vanishing current, i.e.

$$\left(\mu - \frac{\sigma^2}{2}\right) \Delta P(D) = \frac{\sigma^2}{2} \Delta \partial_D (\Delta P)$$

$$\Rightarrow \frac{1}{\Delta P} \frac{d\Delta P}{d\Delta} = \frac{\sigma^2}{2} \left(\mu - \frac{\sigma^2}{2}\right) / \Delta = \frac{1}{\Delta} \left(\frac{2\mu}{\sigma^2} - 1\right)$$

$$\log \Delta P = \log \left(\Delta\right) - 1 + \frac{2\mu}{\sigma^2}$$

$$P(\Delta) = \frac{1}{\Delta} e^{-\frac{\mu}{\sigma^2} \Delta^2 / 2 - \frac{1}{2}}, \quad \Delta > \Delta_{\min}$$

which is normalizable since

$$\underbrace{1 - \frac{2\mu}{\sigma^2}}_{\text{Lévy index}} > 0 \Leftrightarrow \mu - \frac{\sigma^2}{2} \leq 0, \text{ true}$$

$$6) \quad \text{Working with } \tilde{z} = \log S, \text{ we have}$$

$$\dot{\tilde{z}} = + \left(\mu - \frac{\sigma^2}{2}\right) + \sigma \xi(t)$$

and we can draw a parallel with a colloidal object in a gravitational field $-g$ ($g > 0$), at temp T, described by the overdamped Langevin equation:

$$\dot{\tilde{z}} = \tilde{\mu} (-gm) + \sqrt{2D} \xi(t)$$

where $\tilde{\mu} = D/kT$ is the mobility,

and m is the colloid mass. We know that the equilibrium distribution/density is barometric:

$$\tilde{p}(\tilde{z}) \propto e^{-\frac{\tilde{\mu} mg \tilde{z}}{kT}}$$

$$\text{Analogy: } \begin{cases} -mg \tilde{\mu} = \mu - \frac{\sigma^2}{2} \\ \sqrt{2D} = \sigma \\ + \left(\mu - \frac{\sigma^2}{2}\right) \frac{\sigma^2}{\sigma^2} \tilde{z} = \tilde{z} \left(\frac{2\mu}{\sigma^2} - 1\right) \end{cases}$$

$$\Rightarrow \tilde{p}(\tilde{z}) \propto e^{-\tilde{z} \left(\frac{2\mu}{\sigma^2} - 1\right)} = e^{-\tilde{z} \tilde{\mu}}$$

$$\text{Finally: } p(S) = \frac{1}{S} \tilde{p}(\log S) \propto S^{\frac{2\mu}{\sigma^2} - 1}$$

$$7) \quad \dot{S}(t) = \mu' S + \sigma S(t) \xi(t) \quad (5)$$

$$\text{It} \rightarrow \partial_t p(S, t) = -\partial_S \left[\mu' S p \right] + \frac{\sigma^2}{2} \partial_S^2 \left[S^2 p \right]$$

Hence the current is

$$j = \mu' Sp - \frac{\sigma^2}{2} \partial_S (Sp)$$

On the other hand, we get the Shatonovich

$$j = \left(\mu - \frac{\sigma^2}{2}\right) Sp - \frac{\sigma^2}{2} S \partial_S (Sp)$$

We impose the two currents to coincide (ie that the 2 Fokker-Planck equations are the same):

$$\mu' Sp - \frac{\sigma^2}{2} [2Sp + S^2 \partial_S Sp]$$

$$= \left(\mu - \frac{\sigma^2}{2}\right) Sp - \frac{\sigma^2}{2} Sp - \frac{\sigma^2}{2} S^2 \partial_S Sp$$

$$\Rightarrow \mu' = \sigma^2 + \mu - \frac{\sigma^2}{2} - \frac{\sigma^2}{2}$$

$$\boxed{\mu' = \mu}$$

Establishes correspondence
It \Leftrightarrow Shatonovich.

1) Martingales etc.

$$1) \quad \dot{x}(t) = \sqrt{2D} \xi(t)$$

$$\Rightarrow x(t) = x(\Delta) + \underbrace{\int_{\Delta}^t \xi(t') dt'}_{B_{t-\Delta}}$$

$$\langle B_{t-\Delta} \rangle = 0$$

$$\langle B_{t-\Delta}^2 \rangle = 2D(t-\Delta)$$

$$\langle X^2(t) - 2Dt | X(\Delta) \rangle$$

$$= \langle X^2(\Delta) + B_{t-\Delta}^2 + 2X(\Delta) B_{t-\Delta} - 2Dt | X(\Delta) \rangle$$

$$= X^2(\Delta) + 2D(t-\Delta) + 0 - 2Dt$$

$$= X^2(\Delta) - 2D\Delta$$

Hence $X^2(t) - 2Dt$ is a martingale

D-1) From Doob stopping time theorem

$$\langle X^2(\tau) - 2D\tau \rangle = X^2(0) - 0 = 0$$

$$\Rightarrow \langle \tau \rangle = \frac{1}{2D} \langle X^2 \rangle = \frac{a^2}{2D}$$

3) Use again $X(t) = X(s) + B_{t-s}$

$$\begin{aligned} & \langle X^4(t) - \psi(t) | X(s) \rangle \\ &= \langle X^4(s) + 4X^3(s)B_{t-s} + 6X^2(s)B_{t-s}^2 + 4X(s)B_{t-s}^3 \\ &\quad + B_{t-s}^4 - \psi(t) | X(s) \rangle \\ &= X^4(s) + 6X^2(s) \langle B_{t-s}^2 | X(s) \rangle \\ &\quad + \langle B_{t-s}^4 | X(s) \rangle - \psi(t) \end{aligned}$$

and we see that the right-hand side depends on $X^2(s)$, while the left side does not depend explicitly on $X^2(t) \rightarrow$ we cannot find martingales of the proposed form

4) Proceed as above: since B_{t-s} is gaussian of 0 mean: $\langle B_{t-s}^4 \rangle = 3 \cdot \langle B_{t-s}^2 \rangle^2$

$$= 3 (2D(t-s))^2$$

$$\begin{aligned} & \langle X^4(t) - 12DtX^2(t) + \psi(t) | X(s) \rangle \\ &= X^4(s) + 12D(t-s)X^2(s) + 12D^2(t-s)^2 \\ &\quad - 12Dt [X^2(s) + 2D(t-s)] + \psi(t) \\ &= X^4(s) - 12D_s X^2(s) + 12D^2(t-s)^2 \\ &\quad - 12D^2 t (t-s) \times 2 + \psi(t) \end{aligned}$$

We thus require that:

$$\begin{aligned} & \psi(t) + 12D^2(t-s)^2 - 24D^2 t (t-s) = \psi(s) \\ \Leftrightarrow & \psi(t) + D^2(t-s)12[t-s - 2t] = \psi(s) \\ \Leftrightarrow & \psi(t) - \psi(s) = D^2 \cdot 12(t^2 - s^2) \end{aligned}$$

Hence $\boxed{\psi(t) = 12D^2 t^2}$

5) Doob again:

$$\langle X^4(\tau) - 12D\tau X^2(\tau) + 12D^2\tau^2 \rangle = 0$$

$$\Rightarrow a^4 - 12Da^2 \langle \tau \rangle + 12D^2 \langle \tau^2 \rangle = 0$$

$$12D^2 \langle \tau^2 \rangle = -a^4 + 12a^2 \frac{a^2}{2} = 5a^4$$

$$\boxed{\langle \tau^2 \rangle = \frac{5a^4}{12D^2}}$$

6) $\langle e^{\theta X(t)} | X(s) \rangle = e^{\theta X(s)} e^{\theta^2 2D(t-s)/2}$

since $X(t)$ is $g(X(s), \sqrt{2D(t-s)})$

Hence $\boxed{\frac{e^{\theta X(t)}}{e^{\theta X(s)}} = \frac{e^{\theta^2 D(t-s)}}{e^{\theta^2 D(s)}}}$ is a martingale

$$\phi(t) = \theta^2 D t$$

7) $\langle e^{\theta X} e^{-\theta^2 D^2} \rangle = 1$

$$\Rightarrow \langle e^{-\theta^2 D^2} \rangle \left(\frac{1}{2} e^{\theta a} + \frac{1}{2} e^{-\theta a} \right) = 1$$

$$\langle e^{-\theta^2 D^2} \rangle = \frac{1}{\cosh(\theta a)}$$

$$\Rightarrow \boxed{\langle e^{-m D^2 / a^2} \rangle = \frac{1}{\cosh(\sqrt{m})}}$$

8) The above is the moment generating function

Take $\tilde{\tau} = D\tau/a^2$:

$$\langle e^{-m \tilde{\tau}} \rangle = \frac{1}{\cosh \sqrt{m}}$$

$\downarrow n \rightarrow 0$

$$1 - m \langle \tilde{\tau} \rangle + \frac{m^2}{2} \langle \tilde{\tau}^2 \rangle$$

$$\cosh \sqrt{m} = 1 + \frac{1}{2} m + \frac{1}{24} m^2 + O(m^3)$$

$$\frac{1}{\cosh \sqrt{m}} \underset{0}{\approx} 1 - \frac{1}{2} m - \frac{1}{24} m^2 + \frac{m^2}{4}$$

$$\sim 1 - \frac{m}{2} + \frac{m^2}{6} \frac{5}{4}$$

and we recover $\langle \tilde{Z} \rangle = \frac{1}{2}$, $\langle \tilde{Z}^2 \rangle = \frac{5}{12}$

$$\mathbb{D} \langle Z \rangle = \frac{\alpha^2}{2}; \quad \mathbb{D}^2 \langle Z^2 \rangle = \frac{5\alpha^4}{12}$$

D-2) Feynman-Kac

$$Q(x_0) = \left\langle e^{-\int_0^T V(x(t')) dt'} \right\rangle$$

$$\boxed{\mathbb{D} \frac{d^2 Q(x_0)}{dx_0^2} - V(x_0) Q(x_0) = 0}$$

with boundary condition $Q(a) = Q(-a) = 1$
and we also require $Q(x_0) = Q(-x_0)$

$\begin{array}{c} + \\ -a \uparrow \quad a \\ \hline x_0, \text{ start point of walker} \\ \text{Absorbed at } x = \pm a \end{array}$

Since we are interested in $\langle e^{-nD^2/a^2} \rangle$,
we choose $V(x) = nD^2/a^2$

$$\Rightarrow \frac{d^2 Q}{dx_0^2} = \frac{n}{a^2} Q(x_0)$$

$$Q(x_0) = \frac{\cosh(\sqrt{n} x_0/a)}{\cosh(\sqrt{n})}$$

Finally, we have to take $x_0 = 0$,
starting point of the random walk, and

we recover

$$Q(0) = \left\langle e^{-nD^2/a^2} \right\rangle = \frac{1}{\cosh \sqrt{n}}$$

3) We demand that (7)
 $\langle f(x(t), t) | X(s) \rangle$ does not depend on t .
 $\Rightarrow \partial_t \langle \dots \rangle = 0$
 $= \int \partial_t f(x, t) p(x, t | X(s), s) dx$
 $+ \underbrace{\int f(x, t) \partial_t p(\dots) dx}_{= + \mathbb{D} \int f(x, t) \partial_x^2 p dx}$
 $= + \mathbb{D} \int p(x, t | X(s), s) \partial_x^2 f dx$
 $\Rightarrow \partial_t \langle \dots \rangle = \int (\partial_t f + \mathbb{D} \partial_x^2 f) p(x, t | X(s), s) dx$

It is then sufficient to take

$$\partial_t f + \mathbb{D} \partial_x^2 f = 0 \quad (2)$$

Above, we considered

$$f(x, t) = x^2 - 2Dt \quad @$$

$$x^4 - 12Dt x^2 + 12D^2 t^2 \quad @$$

$$e^{\partial_x - \partial^2 D t} \quad @$$

Check that (2) is obeyed:

(a) : $-2D - 2D = 0$, OK

(b) : $-12Dx^2 + 24D^2 t$
 $\mathbb{D}[4 \cdot 3x^2 - 12Dt \cdot 2] = 0$, OK

(c) : $-\mathbb{D}\partial_x^2 e^{\partial_x - \partial^2 D t}$
 $+ \mathbb{D}\partial_x^2 e^{\partial_x - \partial^2 D t} = 0$, OK

And indeed, (2) guarantees that

$f(x(t), t)$ is a martingale

D-3) 1) $\partial_t p(x, t | X(s), s) = \mathbb{D} \partial_x^2 p(x, t | X(s), s)$

2) $\langle f(x(t), t) | X(s) \rangle$
 $= \int f(x, t) p(x, t | X(s), s) dx$