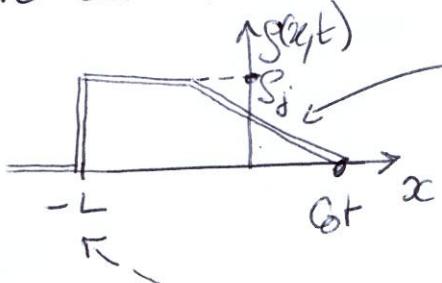


TRAFFIC FLOW

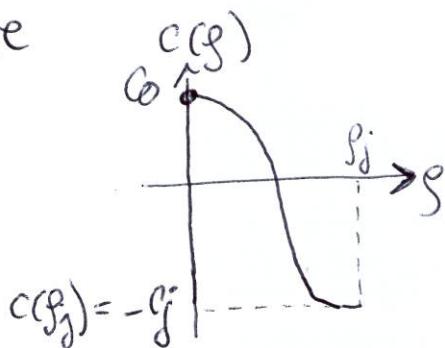
TF1

1/ vehicles around $x=0$ move ahead. the first ones have velocity c_0 . the vehicles at the rear are not moving. One thus has a density profile of the type :

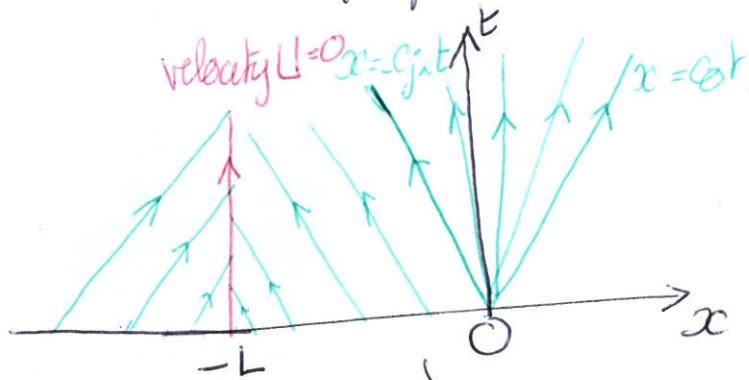


a rarefaction wave is formed ahead, and we will see that the motionless rear end can be considered as a zero velocity shock.

2/ the vehicle's conservation law $s_t + Q_x = 0$ yields $s_t + c(s) s_x = 0$
where



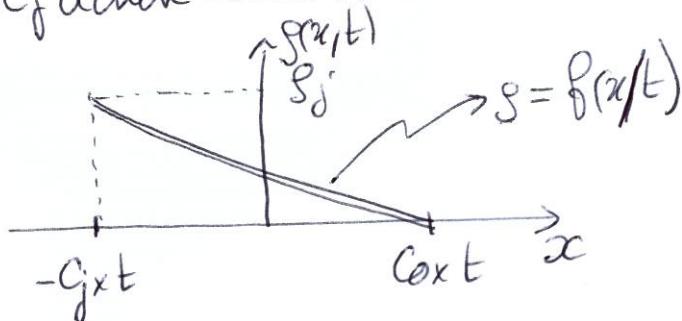
let's draw the characteristics on the (x,t) plane =



The velocity at the rear
(is $\ll 1 = \frac{Q(s_j) - Q(0)}{s_j - 0} = 0$)

for the rarefaction wave =

$$\left\{ \begin{array}{l} x/t \geq c_0 = s \equiv 0 \\ -c_j \leq x/t \leq c_0 = \left[\begin{array}{l} c(s) = \frac{x}{t} \\ \Leftrightarrow s = f(\frac{x}{t}) \end{array} \right] \end{array} \right.$$



it contains a number of vehicles $N_{rw} = \int_{-c_j t}^{c_0 t} s dx$. Since these vehicles were initially at density s_j between $-c_j t$ and 0 one should have $N_{rw} = t c_j s_j$

Let's check it directly: one makes a change of variable $\xi = \xi(x)$ since in the RW $c(\xi) = \frac{\partial \xi}{\partial t}$ one has:

$$d\xi = t \frac{dc}{dp} dp$$

hence $N_{\text{rw}} = \int_{-c_j t}^{t c_0} g d\xi = t \int_{S_j}^0 g \frac{dc}{dp} dp = t [g c(\xi)]_{S_j}^0 - t \int_{S_j}^0 c(\xi) d\xi$

integrating by parts

$[Q(p)]_{S_j}^0 = 0$

thus $N_{\text{rw}} = -t g_j c(c_j) = t c_j S_j$ as expected.

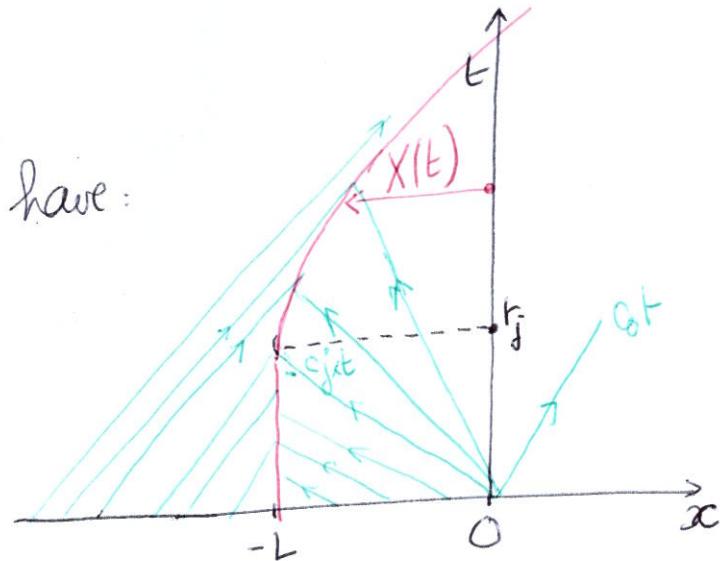
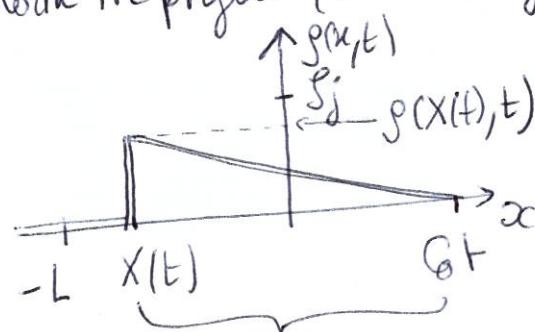
3/ at $t_j = L/c_j$ the rear end of the rarefaction wave reaches $x = -L$. Then, the rear shock begins to move, at velocity $\frac{dx}{dt}$

given by:

$$\frac{dx}{dt} = \frac{Q(g(x,t))}{g(x,t)}$$

and in the (x,t) plane one will have:

with the profile (at $t > t_j$) =



in this region $X(t) < x \leq c_j t$

$$\text{and } g = f(x/t) \Leftrightarrow \frac{x}{t} = c(g) \stackrel{\text{here}}{=} V_m (1 - \frac{g}{g_j})$$

This reads

$$g = \frac{1}{2} g_j \left(1 - \frac{x}{V_m t} \right)$$

The corresponding $Q(g)$ reads:

$$\begin{aligned} Q(g) &= V_m g \left(1 - \frac{g}{g_j} \right) = V_m \frac{g_j}{2} \left(1 - \frac{x}{V_m t} \right) \left[1 - \frac{1}{2} \left(1 - \frac{x}{V_m t} \right) \right] \\ &= \frac{1}{4} V_m g_j \left(1 - \left(\frac{x}{V_m t} \right)^2 \right) \end{aligned}$$

the corresponding equation $\frac{dX}{dt} = \frac{\Phi(p(X(t), t))}{p(X(t), t)}$ reads: (TF3)

$$\frac{dX}{dt} = \frac{1}{2} V_m \left(1 + \frac{X}{V_m t}\right) \quad \text{let's define } y = \frac{X}{V_m t}$$

$$\text{one has } \frac{dy}{dt} = \frac{dX/dt}{V_m t} - \frac{X}{V_m t^2} = \frac{1}{2} \frac{V_m (1+y)}{V_m t} - \frac{y}{t}$$

$$\text{hence } 2t \frac{dy}{dt} = 1-y$$

at $t=t_j$ one has $X=-L$
and here $C_j = V_m$ hence $t_j = \frac{L}{V_m}$, $y(t_j) = -1$

integration: $\frac{dy}{1-y} = \frac{dt}{2t}$ hence $\left\{ \begin{array}{l} 1-y = \frac{K}{\sqrt{E}} \\ \text{with } K = 2\sqrt{\frac{E}{V_m}} \end{array} \right.$

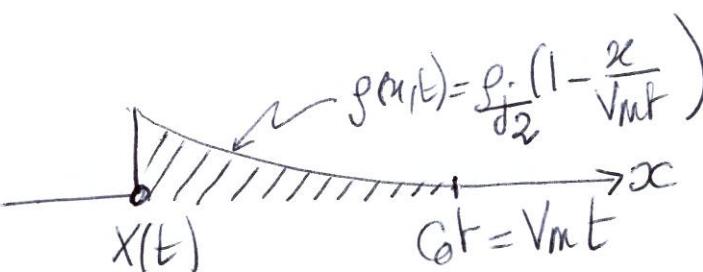
this yields

$$X = V_m t \left(1 - 2\sqrt{\frac{E}{V_m t}}\right)$$

$$X=0 \text{ when } t = \frac{4L}{V_m} = 4t_j$$

at large t one has $X \approx V_m t = Ct$
this is expected from the figure of the characteristics on the previous page-
total

one has a profile =



$=$ straight line - hence the number of vehicles is = (area of the triangle)

$$N_{\text{tot}} = \frac{1}{2} (V_m t - X(t)) \times p(X(t), t)$$

$$\text{this yields } N_{\text{tot}} = \frac{1}{2} 2\sqrt{L V_m t} \times \frac{1}{2} g_j \left(2\sqrt{\frac{E}{V_m t}} \right) = g_j L \text{ as it should.}$$

Note = using the conservation of the # of particles one could have determined $X(t)$ without solving a differential equation -