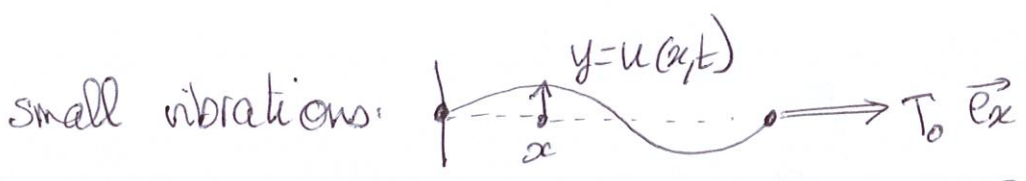


# nonlinear waves and first order equations

Let's start with smthg familiar (neither non linear nor first order)  
 D'Alembert equation for a vibration string - let's consider the situation:

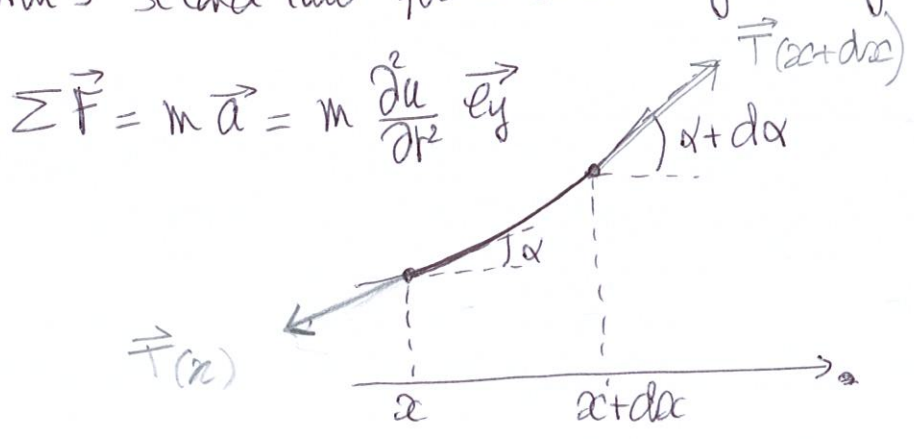


at B one applies a constant force (tension)  $T_0$ .



assumption =  $|\frac{\partial u}{\partial x}| \ll 1$  (notation =  $\frac{\partial u}{\partial x} = \partial_x u = u_x$ )

Newton's second law for a small segment of the string:



$$\left\{ \begin{array}{l} \frac{\partial u}{\partial x} = \tan \alpha \approx \alpha \ll 1 \\ \text{hence } \cos \alpha = 1 + \mathcal{O}(\alpha^2) \end{array} \right.$$

if the gravity is neglected (a guitar sounds the same when it's horizontal or vertical!)  
 one has:

$$T(x,t) \underbrace{\cos \alpha}_{\approx 1} = T(x+dx,t) \underbrace{\cos(\alpha+dx)}_{\approx 1}$$

hence  $T$  is  $x$ -independent, since the tension at B is constant (time indep.)

$$T(x,t) \equiv T_0$$

projecting on the  $y$ -axis =  $T_0 \sin(\alpha + d\alpha) - T_0 \sin \alpha = \rho_0 dl \frac{\partial^2 u}{\partial t^2}$  (2)

$T_0 d\alpha$  where  
 $d\alpha = \frac{\partial \alpha}{\partial x} dx$

$dl \cos \alpha = dx$   
 ( $\rho_0$  is the linear mass density of the string)

one thus has  $u_{tt} - c^2 u_{xx} = 0$   
 where  $c^2 = T_0 / \rho_0$

$c$  is homogeneous to a speed:  $[c^2] = \frac{MLT^{-2}}{ML^{-1}} = (L \cdot T^{-1})^2$

indeed it is a speed of wave propagation:

$\begin{cases} \xi = x - ct \\ \eta = x + ct \end{cases}$

$$\begin{cases} \frac{\partial}{\partial x} = \frac{\partial}{\partial \eta} \frac{\partial \eta}{\partial x} + \frac{\partial}{\partial \xi} \frac{\partial \xi}{\partial x} = \frac{1}{2} (\frac{\partial}{\partial \eta} + \frac{\partial}{\partial \xi}) \\ \frac{\partial}{\partial t} = \frac{\partial}{\partial \eta} \frac{\partial \eta}{\partial t} + \frac{\partial}{\partial \xi} \frac{\partial \xi}{\partial t} = c (\frac{\partial}{\partial \eta} - \frac{\partial}{\partial \xi}) \end{cases}$$

D'Alembert equation:  $[(\frac{\partial}{\partial \eta} - \frac{\partial}{\partial \xi})^2 - (\frac{\partial}{\partial \eta} + \frac{\partial}{\partial \xi})^2] u = 0$   
 $\Leftrightarrow u_{\eta\xi} = 0$

plus eff.  $c = \frac{\partial \xi}{\partial t} = -c$   
 $\frac{\partial^2}{\partial t^2} - c^2 \frac{\partial^2}{\partial x^2} = (\frac{\partial}{\partial t} - c \frac{\partial}{\partial x})(\frac{\partial}{\partial t} + c \frac{\partial}{\partial x})$

the obvious solution is  $u = f(\eta) + g(\xi) = f(x+ct) + g(x-ct)$   
 (solution for an infinite string)  $\nearrow$   
 propagating to the left at velocity  $c$       propagating to the right

parenthesis = how to determine  $f$  and  $g$  starting from the initial shape of the string?

$u(x,0) = f(x) + g(x) \equiv F(x)$   
 $u_t(x,0) = c f'(x) - c g'(x) \equiv G(x)$  = given quantities (ie initial shape and "velocity").

differentiating the 1<sup>st</sup> eq:  $F'(x) = f'(x) + g'(x)$  and combining with the second:

$$\begin{cases} f' = \frac{1}{2} (F' + G/c) \\ g' = \frac{1}{2} (F' - G/c) \end{cases}$$



hence  $f(x) = \frac{1}{2}F(x) + \frac{1}{2c} \int_0^x G(\xi)d\xi + C_1$

$g(x) = \frac{1}{2}F(x) - \frac{1}{2c} \int_0^x G(\xi)d\xi + C_2$

and  $u(x,t) = f(x+ct) + g(x-ct) = \frac{F(x+ct) + F(x-ct)}{2} + \frac{1}{2c} \int_{x-ct}^{x+ct} G(\xi)d\xi + C_1 + C_2$

comme  $u(x,0) = F(x)$  on trouve que  $C_1 + C_2 = 0$ .

simple case  $G(x) \equiv 0$  (no initial speed, just an initial deformation)

there one gets:



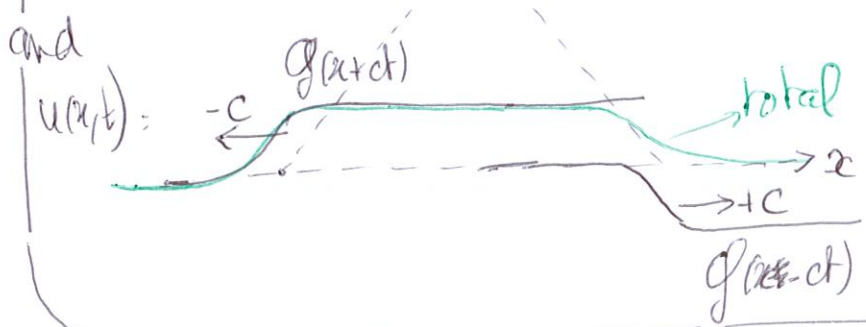
paraphrase = what about the other case =  $F \equiv 0$  &  $G \neq 0$  ?

one has  $u(x,t) = \frac{1}{2c} \int_{x-ct}^{x+ct} G(\xi)d\xi = \frac{1}{2c} \{ \int_{x-ct}^{x+ct} G(\xi)d\xi \}$  where  $\int$  is a primitive of  $G$ .

consider for instance the situation where  $G(x) = u_t(x,0)$  has the shape:



then  $\int$ :



instead of bi-directional motion one can simplify and study the equation:  $u_t - c u_x = 0$ . But now the eq. is made non linear =  $c = c(u)$  = the speed of propagation is a function of the local disturbance  $u(x,t)$ . (4)

Example of a specific problem of this type = traffic flow. Simplified model = only one lane and no overtaking (depassement). Denoting as  $\rho(x,t)$  the car density (# of cars per unit length) and as  $Q(\rho)$  the flux ~~(density)~~ per unit time (debit). one has:

$$\partial_t \rho + \partial_x Q = 0$$

This comes directly from a simple reasoning = the # of cars is conserved and thus the rate of change of the total # of cars in a section  $[x_1, x_2]$  must be balanced by the net inflows across  $x_1$  and  $x_2$  =

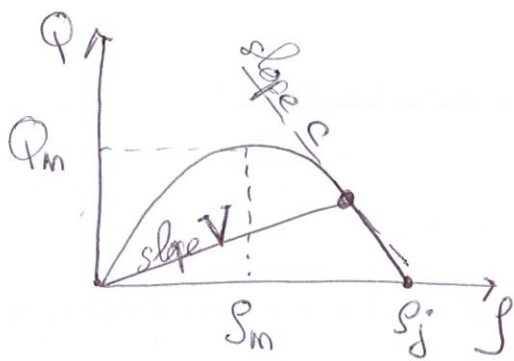
$$\frac{d}{dt} \int_{x_1}^{x_2} \rho(x,t) dx = Q(x_1,t) - Q(x_2,t)$$

and then take the limit  $x_1 \rightarrow x_2$

there is an assumption here:  $Q = Q(\rho)$  = the flux depends only of the local density. there have been some ~~experiments~~ measurements which seem to ~~go in this direction~~ support this assumption.

reasonable form for  $Q(\rho)$ . the flow velocity  $V = Q/\rho$  depends here only on  $\rho$ . It must be a decreasing fct of  $\rho$  which starts from a finite maximum value at  $\rho=0$  and decreases to 0 as  $\rho \rightarrow \rho_j$ , the value for which the cars are bumper to bumper. Thus  $Q(\rho)$  is zero both at  $\rho=0$  and  $\rho_j$  and looks like





The eq.  $\rho_t + Q_\rho = 0$  (5)  
 reads =  $\rho_t + \underbrace{Q'(\rho)}_{c(\rho)} \rho_\rho = 0$

$Q$  has a maximum  $Q_m$  for some value  $\rho_m$  of the car density.

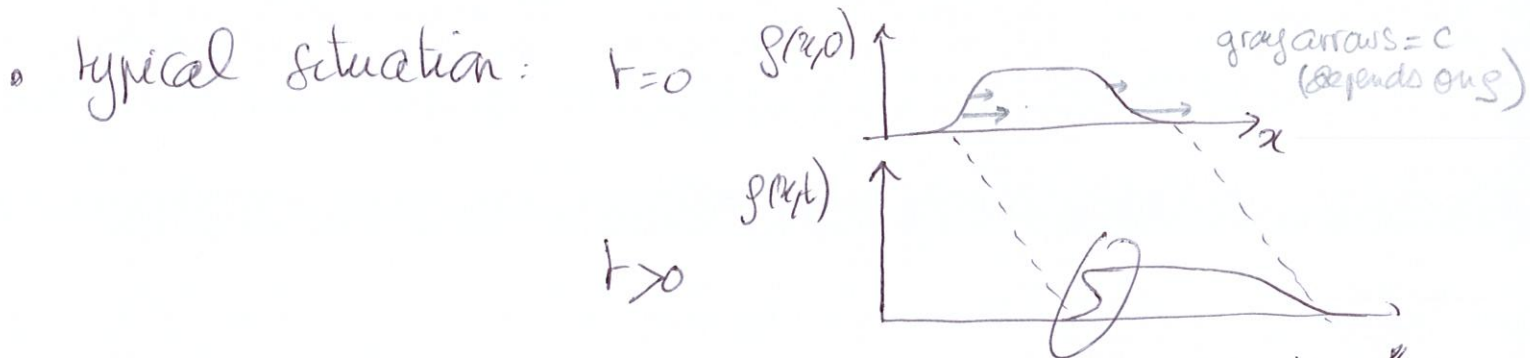
$\rho_j \approx 140$  vehicle/km

$\rho_m \approx 50$  vehicle/km &  $Q_m \approx 1500$  vehicle/hour.

Note that the maximum flow rate is attained at a velocity  $V \approx 30$  km/h (quite low).

The propagation velocity for the wave is  $c(\rho) = Q'(\rho) = V(\rho) + \rho V'(\rho)$   
 Since  $V \downarrow$  as a function of  $\rho$ :  $c(\rho) < V(\rho)$  = waves propagate backward through the stream of traffic and drivers are warned of disturbances ahead.

$c = Q'(\rho)$  hence the traffic wave moves forward or backwards relative to the road depending on whether  $\rho < \rho_m$  or  $\rho > \rho_m$ .



shock = a trailer ~~plus~~ avec plus d'attention.

(PS = traffic flow eqs. can be obtained from car-following theory, cf Whitham p 78)

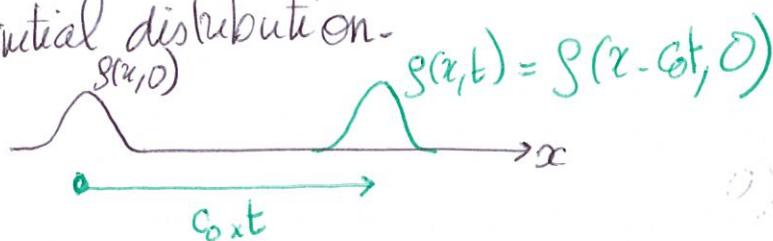
# Method of characteristics

(6)

\*  $S_t + c(g) S_x = 0$

if  $c(g) \equiv c_0$  then we know that  $g(x,t) = f(x - c_0 t)$  [clearly solves the eq. and can be obtained from the change of variable of page 2 = the eq. reads  $S_\eta = 0 \rightarrow g = f(\xi = x - c_0 t)$ ]

where  $f(x) = g(x, 0)$  initial distribution.



\* What happens when  $c(g)$  is not a constant? Formally one can still write  $g(x,t) = f(x - c(g)t)$  where  $f(x) = g(x, 0)$  is the initial distribution

proof =  $S_t = -f' \partial_t [c(g)t] = -f' x [c(g) + t c'(g) S_t]$

$$\Rightarrow S_t = \frac{-c f'}{1 + t c' x f'}$$

$$S_x = f' (1 - \partial_x (c(g)t)) = f' x [1 - t c'(g) S_x]$$

$$\Rightarrow S_x = \frac{f'}{1 + t c' x f'}$$

one has indeed  $S_t + c(g) S_x = 0$

so, for a given  $x$  and  $t$  one could determine  $g$  as a solution of  $x - c(g)t = f^{-1}(g)$ ... this is not very helpful and could miss some important features which are revealed by the method of characteristics (see below)



• first method:  $x - c(p)t = f^{-1}(p) = x_0(p)$

clearly seen by taking  $t=0$  in the equation  $x - c(p)t = f^{-1}(p)$  (7)

hence in the plane

$(x,t)$   $g$  is a constant along

a straight line =  $x = \bar{x} + c(p_0(\bar{x}))t$

↳ inverse of  $p_0(x) = f(x)$  = initial distribution.

for given  $\bar{x}$  ( $\bar{x} = x_0(p_0)$ ) the constant value of  $p$  along the straight line

• second method:

one notices that  $p_t + c(p)p_x$  is the total derivative of  $p$

along a curve, which slope  $\frac{dx}{dt} = c(p)$  since  $\frac{dp}{dt} = p_t + \frac{dx}{dt} p_x$   
 of the  $(x,t)$  plane

Of course the curve  $\mathcal{C}$  which has a slope  $\frac{dx}{dt} = c(p)$  at every of its points cannot be determined explicitly in advance since its definition involves the unknown values of  $p$  on the curve.

However on  $\mathcal{C}$ , from  $\frac{dx}{dt} = c(p)$  and from  $p_t + c(p)p_x = 0$  we deduce

that  $\frac{dp}{dt} = 0 = p$  remains constant  $\rightarrow \mathcal{C}$  is a straight line.  
 as obvious from the equation  $\frac{dx}{dt} = c(p)$

let's then consider the initial value problem =

$$p = f(x) \text{ at } t=0 \text{ for } x \in \mathbb{R}.$$

if one of the curves  $\mathcal{C}$  intersects the axis of abscissae at  $x = \bar{x}$  then  $p = f(\bar{x})$  on the whole of that curve - the corresponding constant slope is  $c(f(\bar{x}))$  which we will denote by  $F(\bar{x}) = c(p_0(\bar{x}))$ .

the equation of the curve is then

$$x = \bar{x} + F(\bar{x})t$$

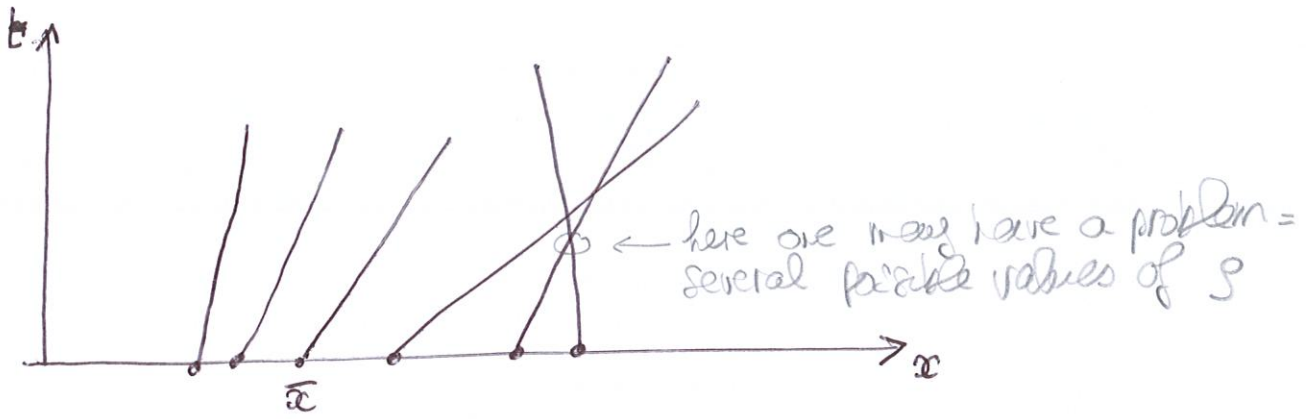
in practice one has the solution in a implicit form =  $p(x,t) = p_0(\bar{x})$  where  $x = \bar{x} + t F(\bar{x})$

[of Whitham] page 61

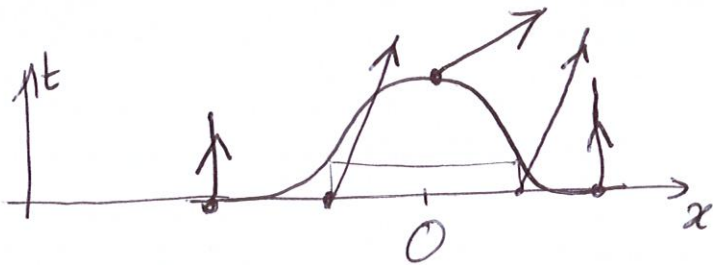
note = in the general case  $p_t + c(p)p_x = b$  where  $b$  and  $c$  are fct of  $p, x$  and  $t$  the method of characteristics works =  $\frac{dp}{dt} = b$  and  $\frac{dx}{dt} = c$  but since  $b \neq 0$   $p$  is not const along the characteristic and generally the characteristics are not straight lines

$u$  has a construction of the following type =

(8)

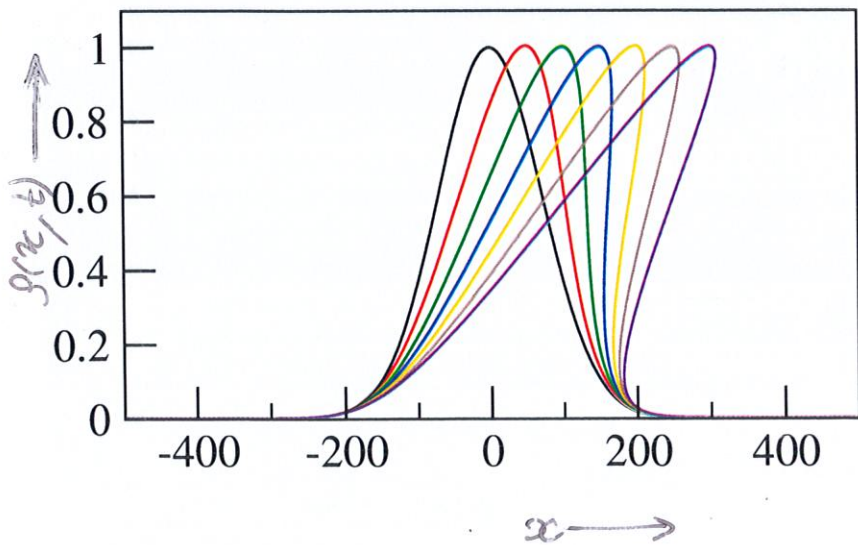


an example = Hopf's equation  $p_t + p p_x = 0$  (ie  $c(p) = p$ ).  
 I take the initial distribution =  $p_0(x) = \exp(-x^2/\sigma^2)$   
 one has:



the numerical solution is ~~immedi~~  
 straightforward = one takes a swarm  
 of initially equi-distant  $\bar{x}$  and  
 they evolve according to  
 $x = \bar{x} + p_0(\bar{x})t$ . For each  $t$   
 one plots  $x(t), p_0(\bar{x}) =$

plot for  $\sigma = 100$



← numerical solution  
 for  $t = 0, 50, 100, \dots, 300$

one observes  
 WAVE BREAKING  
 (at  $t \approx 100$ )

(Remark = notice that the evolution is  
 trivial if the eq. is  $p_t + c_0 p_x = 0$ )



when does breaking occur first? the condition that 2 neighboring characteristics (starting at  $\bar{x}$  and  $\bar{x} + d\bar{x}$ ) intersect is:

$$x = \bar{x} + F(\bar{x})t \quad \text{and} \quad x = \bar{x} + d\bar{x} + F(\bar{x} + d\bar{x})t$$

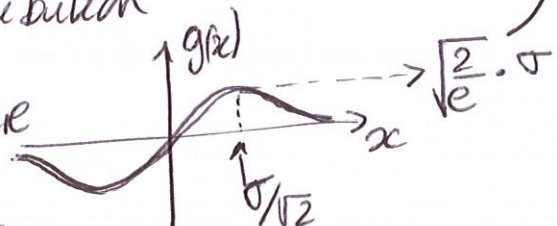
in the limit  $d\bar{x} \rightarrow 0$  this implies  $0 = 1 + F'(\bar{x})t$  hence

$$t = -\frac{1}{F'(\bar{x})} \quad \text{breaking occurs first at } \boxed{t_B = \frac{1}{\max[-F'(\bar{x})]}}$$

exercise = for  $F(\bar{x}) = e^{-\bar{x}^2/\sigma^2}$  (Hopf equation with this initial distribution)

one gets

$$-F'(\bar{x}) = \frac{2\bar{x}}{\sigma^2} e^{-\bar{x}^2/\sigma^2} \equiv g(\bar{x}) \quad \text{where}$$



$$g'(x) = \frac{2}{\sigma^4} e^{-x^2/\sigma^2} (\sigma^2 - 2x^2) \quad \text{cancels}$$

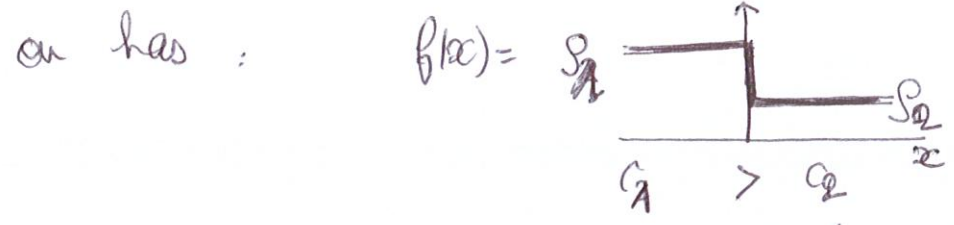
for  $x = \sigma/\sqrt{2}$  and the value of  $g$  is there  $\sqrt{\frac{2}{e}} \frac{1}{\sigma}$

hence  $t_B = \sqrt{\frac{e}{2}} \cdot \sigma \approx 1.1658 \cdot \sigma$  as observed numerically

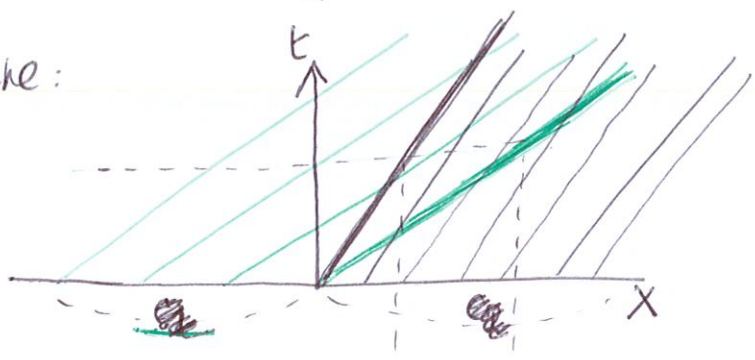
After wave breaking the multivalued solution is not acceptable. We will need a scheme for sorting this out. Before that we will study in more details an extreme case that mathematicians denote as the Riemann problem =

$$p_0(x) = f(x) = \begin{cases} p_2 & x > 0, \\ p_1 & x < 0, \end{cases} \quad \text{and thus } F(x) = \begin{cases} G_2 = c(p_2) & x > 0, \\ G_1 = c(p_1) & x < 0. \end{cases}$$

if  $c_1 > c_2$  then breaking occurs immediately. let's consider for instance the case  $p_1 > p_2$  and  $c'(p) > 0 =$  (in which case  $c_1 > c_2$ )

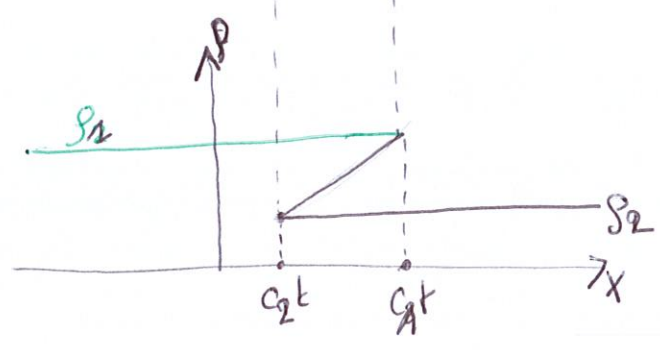


in the  $(x,t)$  plane:

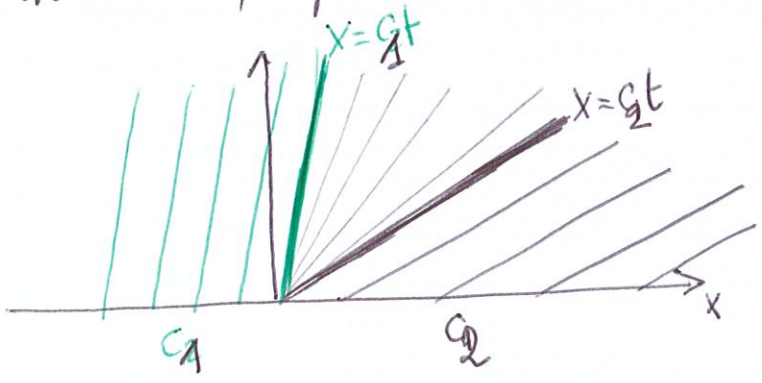
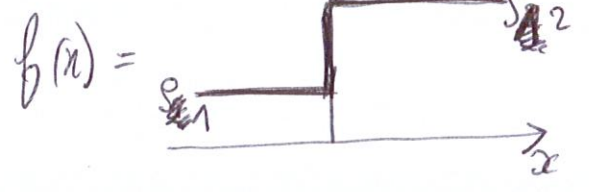


thicker lines  
boundary of the  
multi-valued  
region in the  
 $(x,t)$  plane

at fixed one has:



however if instead one has initially  
then, in the  $(x,t)$  plane =



( $c_1 < c_2$  here)

the "empty" area is filled as follows: remember that  $\bar{x} = \bar{x} + F(\bar{x})t$   
 one takes  $\bar{x} = 0$  and  $F(\bar{x})$  going from  $c_2$  to  $c_1$  = this leads  
 to the gray lines of equation  $x = Ft$  for  $c_1 < F < c_2$   
 this procedure is exactly the sharp limit of  $p_1$  to  $p_2$   
 when  $\epsilon \rightarrow 0$ .

since here  $c = F$  one has  $c = x/t$   
 for  $c_1 < x/t < c_2$

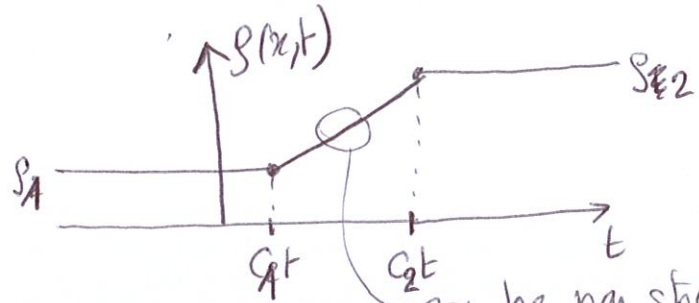


The complete solution for  $c$  is then:

$$c = \begin{cases} c_2 & \text{for } c_2 < x/t \\ x/t & \text{for } c_1 < x/t < c_2 \\ c_1 & \text{for } x/t < c_1 \end{cases}$$

then the value of  $S$  is obtained by inverting the relation  $c = c(\rho)$ .

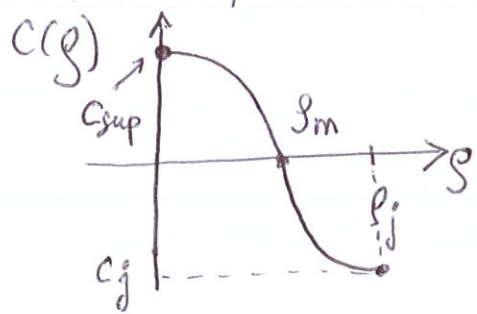
one gets smthg like = which is perfectly acceptable



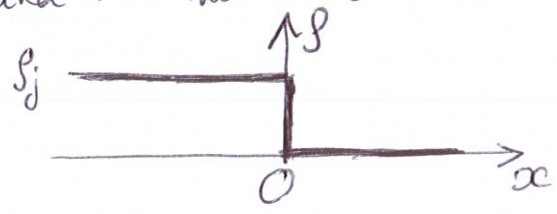
can be non straight line if the relation  $c = c(\rho)$  is not linear

example = describe what happens after a traffic light turns green.

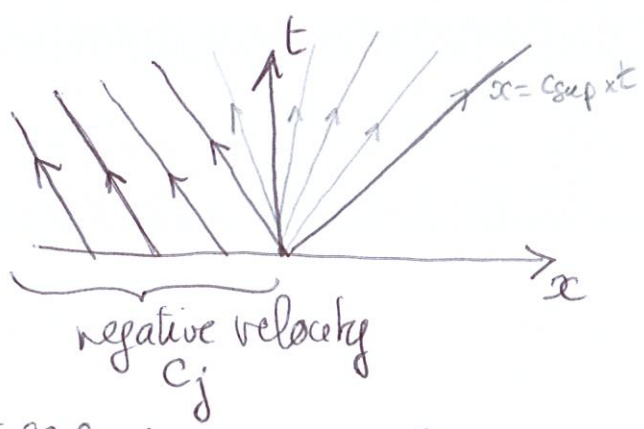
from the qualitative behavior of  $Q(\rho)$  (cf page 5) one has



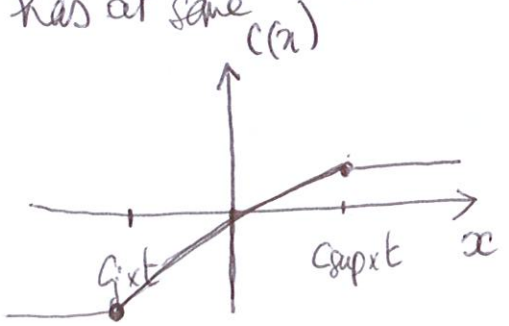
and the initial distribution is:



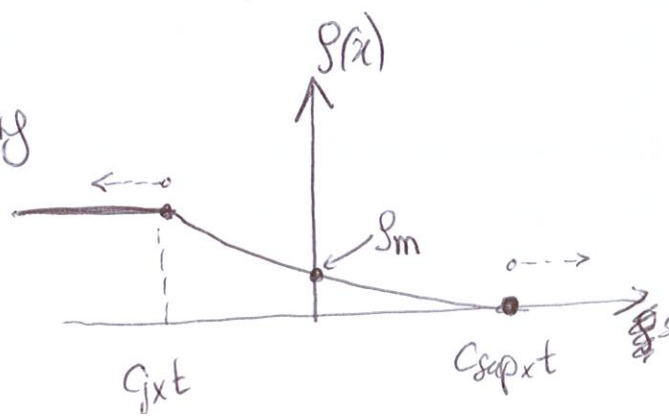
so one gets:



thus one has at some finite t:



leading to:



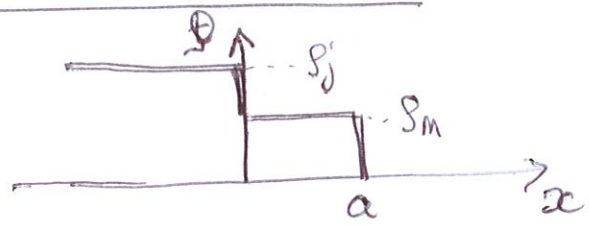
exercice =

assume that the initial distribution is

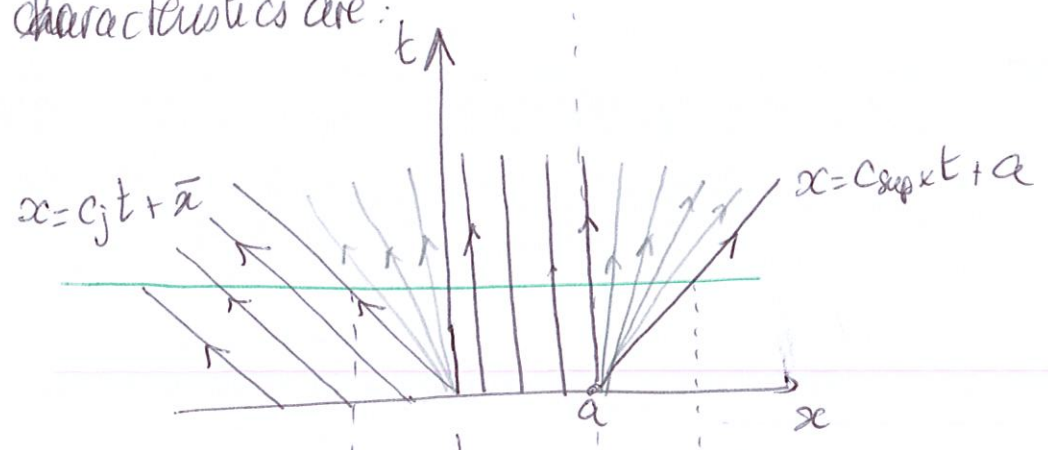
$$S = \begin{cases} S_j & \text{for } x < 0 \\ S_m & \text{for } 0 < x < a \\ 0 & \text{for } x > a \end{cases}$$

describe what happens at  $t > 0$

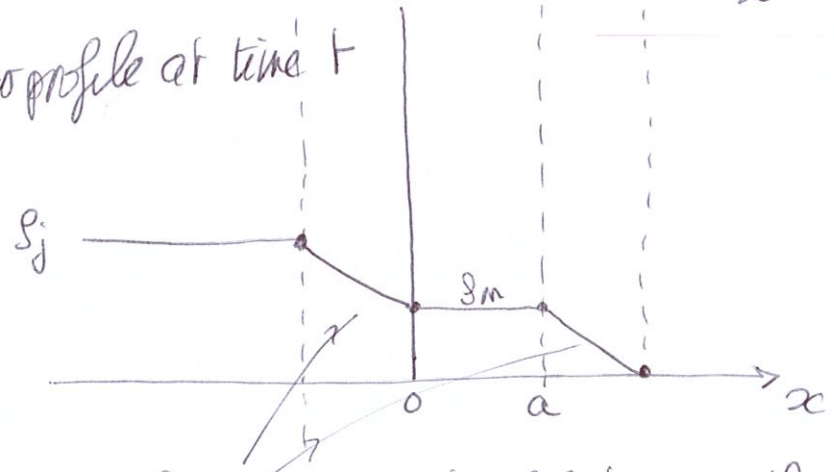
one has:



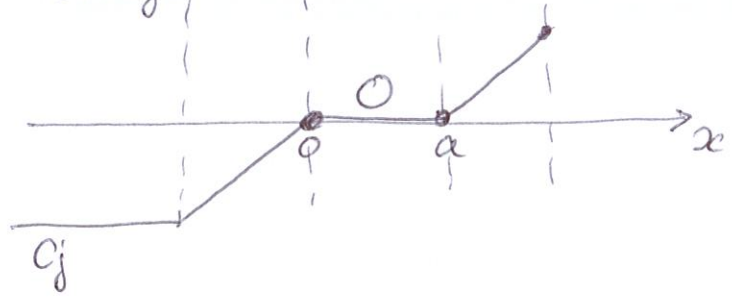
thus the characteristics are:



and the ~~flow~~ profile at time t



here the curve is bended because the relation  $c = c(c_j)$  is not an exact straight line, but  $c$  plotted as a function of  $x$  is a series of straight lines:



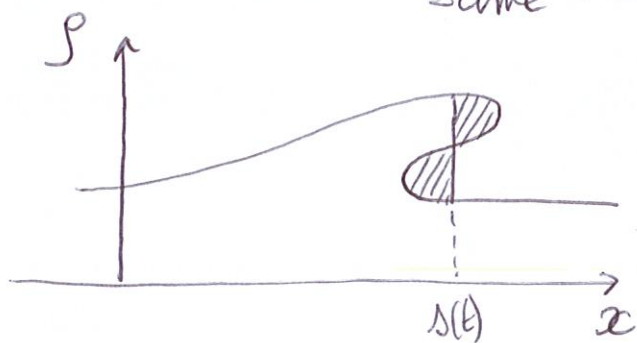


Shock waves.

the multivalued solution (of page 8) is <sup>(12)</sup> (often) unacceptable  $\sim$ . ~~the~~ One has an

abrupt solution = replace ~~the~~  $\sim$  by  $\nabla$   
↓  
shock

the correct position for the discontinuity may be determined by the following argument = both the multivalued curve and the discontinuous curve satisfy conservation law. Therefore Spdc under each curve & must be the same  $\rightarrow$  equal area law =



this determination is not very convenient for analytic work...

velocity of the shock = one could argue that an eq. of the form  $p_t + c(p) p_x = 0$  doesn't like discontinuity. But remember that it has an integrated form =

~~the~~  $p_t + Q_x = 0$  <sup>has been obtained from</sup> ~~the~~  $\frac{d}{dt} \int_{x_1}^{x_2} p(x,t) dx + Q(x_2,t) - Q(x_1,t) = 0$

and this guy doesn't mind discontinuous  $p$  or  $Q$ . ( $x_1$  and  $x_2$  fixed, i.e. independent of  $t$ )

let's denote by  $s(t)$  the position of the shock. and ~~the~~ take in the above  $x_1 < s(t) < x_2$ .

One will have:

$$\frac{d}{dt} \left( \int_{x_1}^{s(t)} p(x,t) dx \right) + \frac{d}{dt} \left( \int_{s(t)}^{x_2} p(x,t) dx \right) = Q(x_2,t) - Q(x_1,t)$$

$$\Rightarrow p(s^-,t) \dot{s} - p(s^+,t) \dot{s} + \int_{x_1}^{s(t)} p_t(x,t) dx + \int_{s(t)}^{x_2} p_t(x,t) dx = 0$$

then take the limit  $x_1 \rightarrow s^-$  and  $x_2 \rightarrow s^+$ , one gets

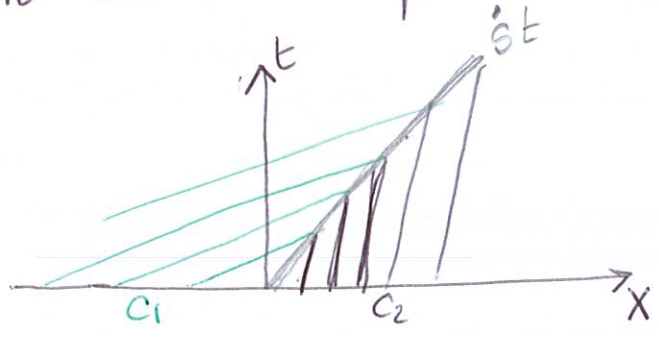
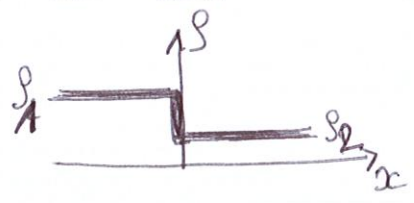
$$s = \frac{Q^+ - Q^-}{s^+ - s^-} = \frac{Q(s^+) - Q(s^-)}{s^+ - s^-}$$

note that this reasoning is the same as the one which led to the equal area rule: one has:

$$\begin{array}{c|c} \uparrow \dot{s} & \\ \hline s = s^- & s = s^+ \\ Q = Q(s^-) & Q = Q(s^+) \end{array}$$

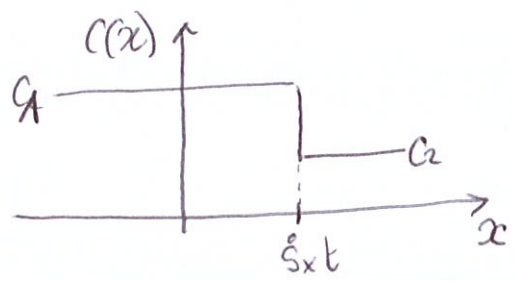
and the shock moves at a velocity such that the conservation law is verified.

• one can then return to our Riemann problem (page 10)

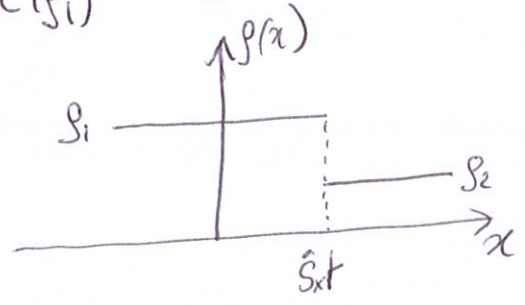


note = here  $Q(\rho) = \int c$  and we have assume that  $c'(\rho) > 0$  hence  $Q$  is convex. As a result  $c(\rho_2) < \dot{s} < c(\rho_1)$  as it should.

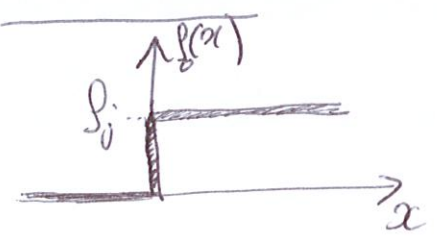
one has:  
argument



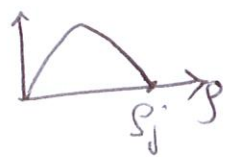
and



question = how does evolve the end of a traffic jam?



answer = remember that  $Q(\rho)$  hence  $\dot{s} = 0$

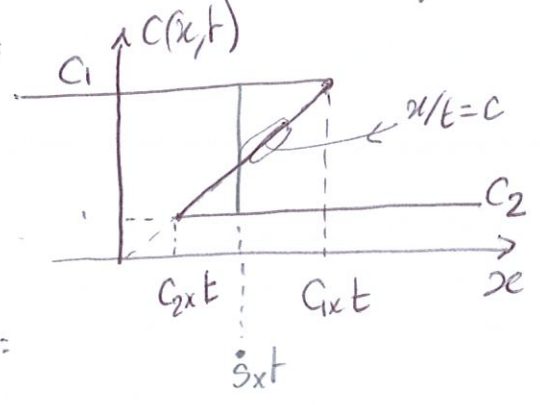




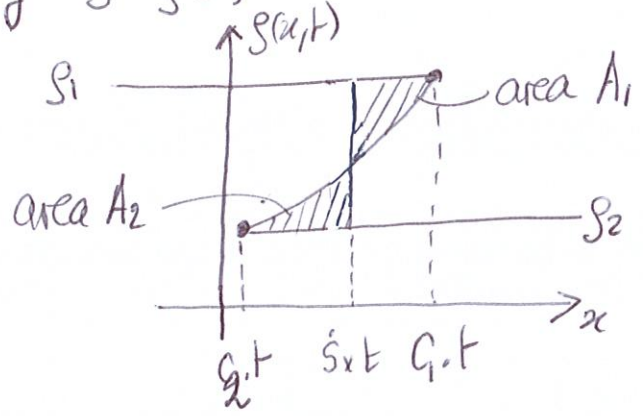
large parentheses, main question legitimate =

does any solution of the Riemann pb fulfill the equal area law?

one has for  $c(x)$  at time  $t$ :



and the shape of  $\rho$  is given by applying  $\rho = \rho(c)$  to this curve:



$$A_1 = \int_{s \cdot t}^{c_1 \cdot t} (\rho_1 - \rho(c = \frac{x}{t})) dx$$

$$A_2 = \int_{c_2 \cdot t}^{s \cdot t} (\rho(c = \frac{x}{t}) - \rho_2) dx$$

change of variable =  $c = \frac{x}{t}$   $dx = t dc =$

$$A_1 = t \int_{\dot{s}}^{c_1} (\rho_1 - \rho(c)) dc$$

$$A_2 = t \int_{c_2}^{\dot{s}} (\rho(c) - \rho_2) dc$$

notas  $R(c)$  une primitive de  $\rho(c)$  [ $R(c) = \int_{c_0}^c \rho(c') dc' \Leftrightarrow \frac{dR}{dc} = \rho(c)$ ]  
 also

$$\frac{A_1}{t} = \rho_1 (c_1 - \dot{s}) - R(c_1) + R(\dot{s}) \text{ et } \frac{A_2}{t} = R(\dot{s}) - R(c_2) - \rho_2 (\dot{s} - c_2)$$

$$\text{donc } A_1 = A_2 \Leftrightarrow \dot{s} (\rho_2 - \rho_1) = [\rho_2 c_2 - R(c_2)] - [\rho_1 c_1 - R(c_1)]$$

it ça marche because the r.h.s is equal to  $Q(\rho_2) - Q(\rho_1)$  hence  
 $A_1 = A_2 \Leftrightarrow \dot{s} = \frac{Q(\rho_2) - Q(\rho_1)}{\rho_2 - \rho_1}$  which is the definition of  $\dot{s}$ . so every thing's ok

(\*) The rhs is  $Q(\rho_2) - Q(\rho_1)$  because the function  $Q(\rho) = \rho c(\rho) - R(\rho)$  is equal to  $Q(\rho)$  up to a constant =  $\frac{d}{d\rho} Q = c + \rho \frac{dc}{d\rho} - \frac{dR}{d\rho} \cdot \frac{dc}{d\rho} = c = \frac{dQ}{d\rho}$