

# Lossy data compression with random gates

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We introduce a new protocol for a lossy data compression algorithm which is based on constraint satisfaction gates. We show that the theoretical capacity of algorithms built from standard parity-check gates converges exponentially fast to the Shannon's bound when the number of variables seen by each gate increases. We then generalize this approach by introducing random gates. They have theoretical performances nearly as good as parity checks, but they offer the great advantage that the encoding can be done in linear time using the Survey Inspired Decimation algorithm, a powerful algorithm for constraint satisfaction problems derived from statistical physics.

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*Introduction.* Constraint satisfaction problems (CSPs) are at the heart of an emerging field of research which is of interest to statistical physics, combinatorial optimization, statistical inference and information theory [1]. Broadly speaking, these are problems involving a large number of variables, taking values in a finite set (hereafter we shall keep to binary variables). Each constraint involves  $K$  variables, and imposes a probability law on the  $2^K$  possible assignments of the variables in this subset. Hard constraints just forbid some of the configurations. The spin glass problem [2], the satisfiability problem which lies at the heart of the theory of computational complexity in computer science [3], or the parity check problems used in error correcting codes [4] all belong to this category.

A lot of progress has been made in recent years in the study of random constraint satisfaction problems where each constraint involves randomly chosen (with uniform distribution) variables [5]. This is the natural setting for spin glasses, it offers the possibility to study issues in typical case complexity in satisfiability, and it provides some of the most efficient codes for error correction. In several cases, it has been found that when the density of constraints increases the system enters first a 'clustered' phase before it reaches the threshold of unsatisfiability where it cannot meet all the constraints. Above this threshold the configurations which violate the smaller number of constraints are also clustered. Clustering means that the configurations which satisfy all the constraints are grouped into many disconnected clusters which are distant from each other. Statistical physics methods originating from spin glass theory, like the replica and cavity methods, turn out to be very efficient to study these phenomena [6, 7], and some of the results have been confirmed rigorously recently [8, 9, 10, 11]. They have also led to a powerful algorithm (survey propagation) which is able to solve very large problems in the clustered region [7].

We will show how one can take advantage of these

clustered phases to address a classic problem in coding theory, lossy data compression. While a large amount of work has been done in this field [12], a number of challenging problems are open, among them the realization of a practical compression protocol for correlated sources or the exponential increasing time in the encoding/decoding step of typical algorithms. As for lossy compression schemes, it is worth to mention in particular the good performance of algorithms based on the codes [13] developed in the context of channel coding. Here we propose an alternative strategy, and as a starting point we focus on the case of uncorrelated sources.

The problem of lossy data compression can be summarized as follows. We have a source alphabet  $\mathcal{A}$ , a source distribution  $p(x_a)$  and a distortion measure  $d(\cdot, \cdot)$  which takes values in  $[0, 1]$ . We start from an original message which is a sequence  $\{x_a\}$  of  $M$  values independently drawn from the source distribution. The purpose of data compression is to map this message to a string of  $N$  bits, with  $N < M$ , in such a way that they can be for example easily transmitted or stored. Then, one wants to decode this  $N$ -bits string in order to reconstruct a sequence as close as possible to the original message. We call the decoded message  $\{x_a^*\}$  and we want to minimize the expected value of the distortion  $D \equiv \mathbb{E} \sum_{a=1}^M d(x_a, x_a^*)/M$ . How small a distortion one can achieve depends on the rate  $R = N/M$  at which the original message has been compressed.

The rate distortion theorem proved by Shannon [14] provides a bound for the minimum rate at which a compression is possible once we fix the average distortion we tolerate. The analytic expression of this *rate-distortion function*  $R(D)$  is not known explicitly in the most general case of correlated (memory) sources, and it is most often obtained by means of some numerical algorithm (see e.g. [15]). On the other hand, for an uncorrelated unbiased binary source (i.e. with  $p(x_a = 0) = 1 - p(x_a = 1) = 1/2$ ), the rate-distortion function in the large  $N$

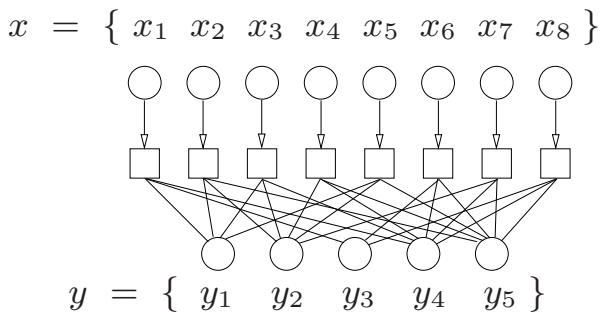


FIG. 1: A Tanner graph is a convenient representation for a CSP. We emphasize in this cartoon the topological support of our protocol.

limit has the simple expression

$$R(D) = 1 + D \log_2 D + (1 - D) \log_2(1 - D). \quad (1)$$

As a first requirement, a good lossy data compression algorithm must be able to approach this theoretical limit. One should mention that in the lossless case, that is the  $D \rightarrow 0$  limit, practical algorithms that saturate asymptotically the Shannon's bound have been discovered a long time ago [16]. The lossy case turns out to be more difficult from the algorithmic point of view. Recently, a perceptron with a non-linear transfer function has been proposed [17] as a lossy compressor and it has been analytically shown to achieve theoretically optimal performance, but its practical use is strongly reduced by the fact that there is no known polynomial algorithm in this case, and the typical string lengths that can be compressed in reasonable time are thus rather short.

*The general idea.* We are interested here in developing an approach to the problem which is based on CSPs, as suggested in [18]. Our CSP uses  $M$  constraints between  $N$  Boolean variables taking values in  $\{0, 1\}$ . Each constraint, say  $a$ , is actually a gate controlled by the value  $x_a$  of the  $a$ -th bit of the original message (see Fig. 1). The gate  $a$  is connected to  $K_a$  randomly chosen variables. The  $2^{K_a}$  possible configurations of these variables are partitioned into two equal size subsets,  $S_a$  and  $U_a$ . When the control bit is  $x_a = 0$ , the configurations in  $S_a$  satisfy the constraint, the configurations in  $U_a$  don't. When the control bit is  $x_a = 1$ , the configurations in  $U_a$  satisfy the constraint, the configurations in  $S_a$  don't. A simple example is provided by parity checks.  $S_a$  consists of the configurations with an even number of 0's. The gate then performs a linear operation: it checks whether the sum of all variables and  $b_a$  is equal to 0 modulo 2. In this case the CSP is nothing but the well known XOR-SAT problem in computer science [19]; it can also be seen as a spin glass problem with three-spin interactions.

In our procedure, the initial word of  $M$  bits is used to build a CSP with  $M$  constraints for  $N$  ( $< M$ ) variables  $\{y_1, \dots, y_N\}$ . We then look for a configuration of

variables  $\mathbf{y}^*$  that minimizes the number of violated constraints, that is ground state configuration. This is the encoded (compressed) word. Of course, this step is non-trivial since one must be able to handle a CSP which is in its "unsat" phase. We note that the rate  $R$  of the process is simply related to the density of constraints  $\alpha = M/N$  by  $R = 1/\alpha$ . Once we have a ground state configuration, the decoding is easy: for each constraint  $a$ , one considers the configuration of the subset of  $K_a$  variables appearing in  $a$ . If it lies in  $S_a$ , the reconstructed bit is  $x_a^* = 0$ , otherwise it is  $x_a^* = 1$ . The number of bits of the original message which are wrongly reconstructed is nothing but the number of constraints violated in a ground state configuration.

We shall measure the distortion as  $D = \sum_{a=1}^M |x_a - x_a^*|/M$ . We define the total "energy" of a configuration  $\mathbf{y}$  of the CSP as  $E(\mathbf{y}) = \sum_{a=1}^M \varepsilon_a$ , where  $\varepsilon_a(\mathbf{y}) = 0$  if the constraint  $a$  is satisfied by the global configuration  $\mathbf{y}$ , and  $\varepsilon_a(\mathbf{y}) = 1$  otherwise. The distortion is then related to the ground state energy  $E_0$  of the CSP through:

$$D = E/M. \quad (2)$$

We are interested in the thermodynamic limit  $N, M \rightarrow \infty$  at fixed density of constraints  $\alpha$ . Shannon's theorem provides a lower bound  $E_{Sh}(\alpha)$  to the ground state energy, and a good compression algorithm should be based on a CSP with a very low ground state energy, as near as possible to Shannon's value.

The coder based on parity check gates (XORSAT-CSP) is a good candidate. A general strategy for computing the ground state energy of this problem has been developed in [8]. When all checks involve  $K$  variables and  $K$  becomes large, a computation based on this strategy [20] shows that  $E_0(\alpha) - E_{Sh}(\alpha)$  decreases exponentially with  $K$ . So the theoretical capacity of these gates rapidly approach Shannon's limit when  $K$  increases. Unfortunately there is no known algorithm which matches this theoretical capacity. This is in contrast to the use of low density parity check codes for channel coding, where message passing techniques are known to perform quite well. However we shall see below that message passing does perform well on some other classes of gates.

*Message passing* Useful techniques for solving random CSPs are based on local iterative updates of some "messages" sent along the graph. For example, applying the 'Min-Sum' algorithm [21] to CSPs, one obtains the Warning Propagation (WP) algorithm: each constraint  $a$  sends a warning message  $u_{a \rightarrow i}$  to one neighbor variable  $i$  according to the values of the other variables attached to it: This message can be 0 – meaning that the variable is free to assume any value [23] – or 1 – meaning that, in order to satisfy that constraint, the variable should assume a certain value –. This algorithm is very powerful and efficient in many CSPs where the underlying factor graph is locally tree-like, when the density of constraints is small

enough. However it is limited in two aspects: 1) it stops to converge when the density of constraint is such that the system is in a clustered phase, and in particular in the unsat regime which is of interest for our compression scheme. 2) It does not work for parity checks because of the basic symmetry of these gates.

The first limitation can be handled by going to a more sophisticated message passing algorithm, Survey Propagation (SP). The SP algorithm is the direct implementation of the 1RSB cavity equations on a single sample. In this case, one works with the probability distribution  $Q_{a \rightarrow i}(u_{a \rightarrow i})$  that, if we pick one cluster at random, the warning  $u_{a \rightarrow i}$  is sent along the link from constraint  $a$  to variable  $i$ . This is the general object which is needed in order to cope with the appearance of disconnected clusters of solutions. Once we know the probabilities of all the warnings, we estimate the probability of the total bias  $H_i$  on the variable  $i$ , defined as  $H_i = \sum_{a \in V(i)} u_{a \rightarrow i}$ , where  $V(i)$  is the set of constraints attached to the variable  $i$ . The idea behind the Survey Inspired Decimation (SID, [7]) is to take advantage of this information to fix the most biased variable in the system. Once this is done, one has a simplified CSP with  $N - 1$  variables and we can thus repeat this step until one is left with an under-constrained problem solvable by some standard local algorithm. This algorithm has been shown to be very useful in CSP problems like the coloring or the K-SAT, where one is able to find efficiently a SAT assignment in the difficult region. It can also be used for problems with higher constraint density in order to find configurations of low energy (small number of violated constraints) [22], which makes it a very useful tool for compression.

*Non-linear nodes.* While it performs well on many CSPs, the SP algorithm is useless for the “parity source coder”. The problem here comes from the fact that the distribution of the total bias is always symmetric, so that the messages obtained after convergence give no hint of how to decimate the problem. In order to solve this problem, we propose a compression scheme based on some other gates, different from parity checks. These turn out to have a theoretical capacity close to the parity checks, and a generalized version of the SP algorithm [20] leads to a convergent decimation scheme which is an efficient coding algorithm. Among the several types of constraints we have examined, the “random” nodes have been found to be the more efficient. They are defined as follows: The subset  $S_a$  is a randomly chosen subset of size  $2^{K-1}$ . While parity checks just implement linear constraints on  $Z_2$ , these random nodes are non-linear functions of their inputs. However from the point of view of the cavity method (used to compute their theoretical performance) and of the SP message passing procedure (used as encoding algorithm), they can be handled by relatively straightforward generalizations of the methods used for parity checks [20]. In this note we summarize the results.

We build up a list of  $r$  random checks, and each con-

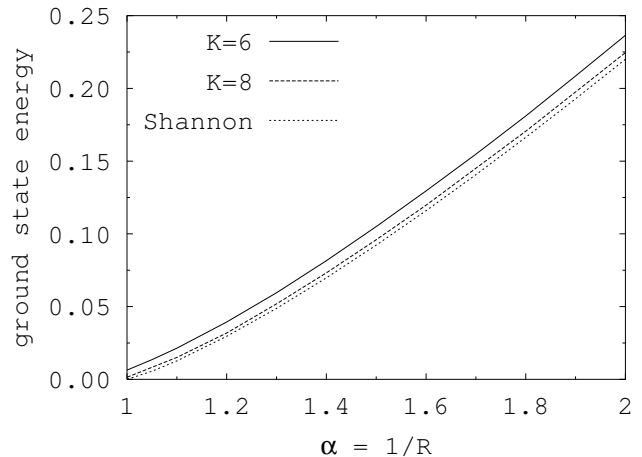


FIG. 2: The ground state energy of the CSP based on non-linear nodes versus the constraint density  $\alpha$ . Shannon's bound is also plotted for comparison.

straint  $a$  picks up one check randomly in this list [24]. This allows to memorize the truth table of all nodes and thus to speed up the algorithms. All the results quoted below are for  $r = 30$ . The theoretical capacity of this system, which is proportional to the ground state energy according to (2), is illustrated in Fig. 2. As we clearly see, the ground state quickly approaches the Shannon's bound of Eq. (1) as  $K$  increases. Thus, this particular CSP is very promising from the point of view of lossy data compression. In Fig. 3 we show the phase diagram for  $K = 6$ . The *static* energy is the ground state energy per variable also plotted in Fig. 2; from the algorithmic point of view, this is the performance of the best possible algorithm which minimizes the number of violated constraints. The *dynamical* energy marks the appearance of a regime where solutions group in many different well separated clusters (that is, in order to go from one cluster to another one we should flip an extensive number of variables); any local algorithm, as for example WP, will be trapped at this dynamical threshold. The dynamical energy computed here in the 1RSB approximation is believed to be an upper bound to the exact one. Finally, the stability curve [9] indicates the range of validity of the 1RSB formalism used to determine this phase diagram (in particular, the ground state energy which we compute should be the exact one for  $\alpha < \alpha_{1rsb}$ ).

So the theoretical properties of the random-node CSP are quite similar to the parity check CSP (the XORSAT problem discussed in [8]). The good point with respect to the parity check CSP is that in this case the SID algorithm does converge in the unsat phase in a time which scales as  $2^K N \log N$ , and gives very low energy states, *i.e.* nearly optimal global configurations. In Fig. 4 we show the performance of the compressor based on ran-

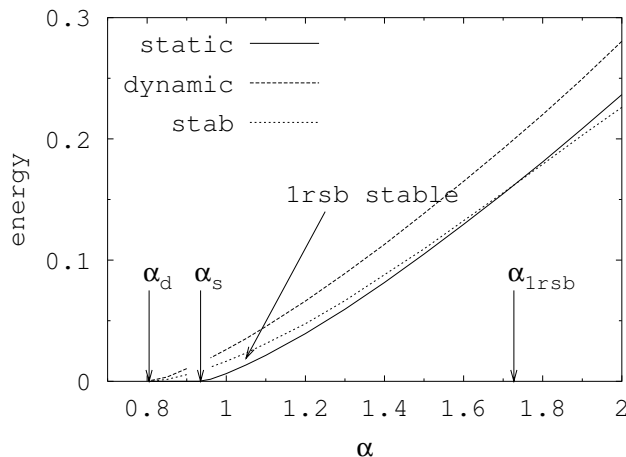


FIG. 3: The phase diagram of a system with 30 different random nodes with  $K = 6$ . The values for the thresholds are:  $\alpha_d = 0.803$ ,  $\alpha_s = 0.935$  and  $\alpha_{lrsb} = 1.727$ .

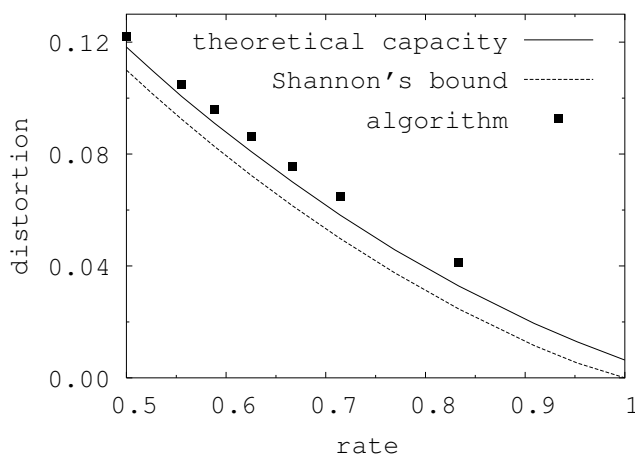


FIG. 4: The performance of the algorithm is plotted versus the rate  $R = 1/\alpha$  of the compression (here  $K = 6$ ,  $N = 1000$ ), together with the theoretical capacity and Shannon's bound.

dom gates, for  $K = 6$ . The distortion achieved in practice by the algorithm with  $N = 1000$  is close to the theoretical capacity, which brings it a few % above Shannon's bound. As shown in Fig. 2, we expect the performance to improve with increasing  $K$  (at the price of an increase in computer time).

**Conclusions.** We have shown, by using techniques borrowed from the statistical physics of disordered systems, how one can use CSPs as a tool for compressing data. In particular, the algorithmic performance of the random gates – CSPs based on non-linear nodes – is found to be nearly optimal, since the Shannon bound is reached

at large  $K$ . The generalization of the present approach to compression of data from a larger alphabet (beyond binary input) looks like an interesting perspective.

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  - [23] A variable is free when the status of the constraint ( $\varepsilon_a = 0$  or 1) is independent of the actual value of the variable.
  - [24] We forbid “fully canalizing” nodes that just depend on one variable.